

View Independent Environment Mapping with Dual Paraboloid Maps

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Environment Map Problem

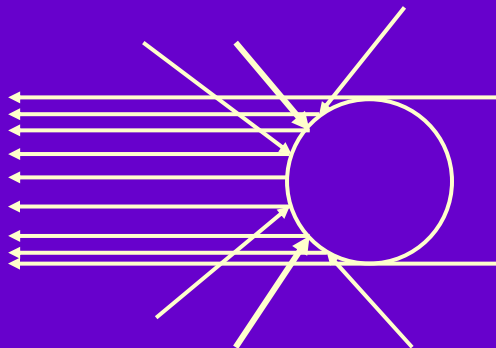
- Sphere mapping is view dependent
- Requests constant regeneration of sphere map texture for changing viewpoints
- Must be a better way!

There is!

- Wolfgang Heidrich & Hans-Peter Seidel have proposed a view independent environment mapping scheme
- No special hardware requirements
- Uses two environment textures, each with a parabolic basis

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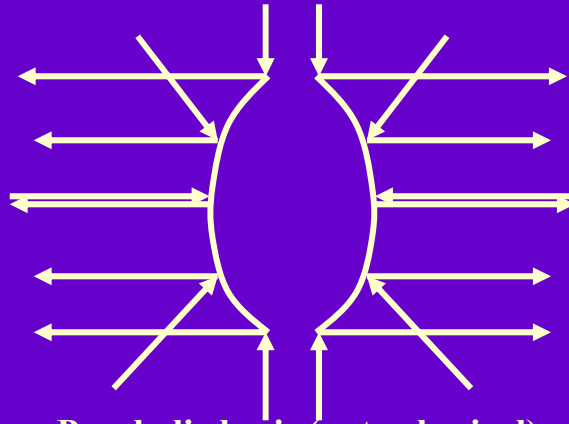
Sphere maps work like this



Sphere collects environment image

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Dual paraboloid approach



Parabolic basis (not spherical)
Requires two texture images

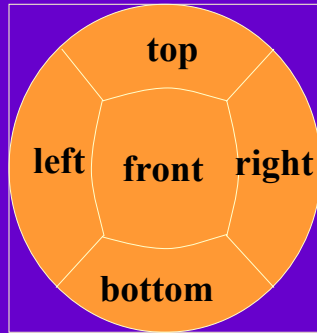
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Advantage

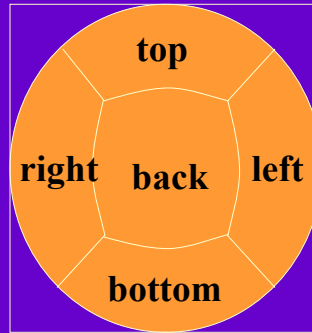
- Dual paraboloid maps capture complete environment with no singularities
- Linear basis
- Well suited for dual-texture hardware such as the RIVA TNT
- View independent!

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Dual Paraboloid Map



front texture

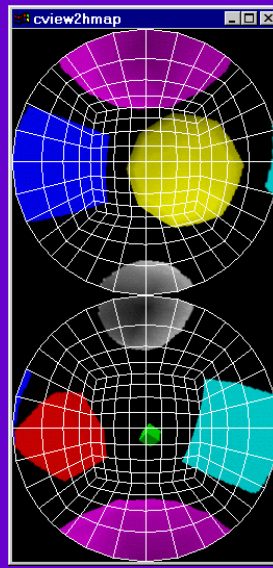
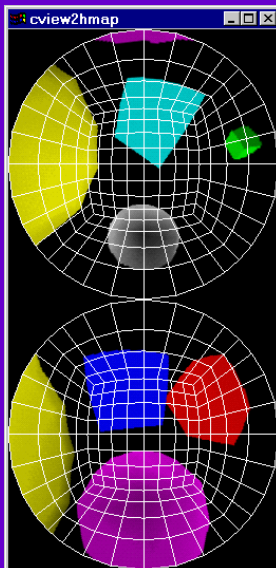


back texture

alpha=1.0 inside circle,
alpha=0.0 outside circle

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In practice



meshes
added
for clarity

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Issues

- Must have way to “pick” environment from the correct texture of the two for a given pixel
 - Alpha testing works in two passes
 - The blend texture environment works will for ARB_multitexture
- Rotation needed to supply view independence & projection needed
- Think texture matrix and perspective correct textures!

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Two pass approach

- Adjust texture matrix for front view
- Bind to “front” paraboloid map
- Draw object with reflection map texgen, alpha test away non-unity alpha
- Adjust texture matrix for back view
- Bind to “back” paraboloid map
- Draw object same as before

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Texture Matrix Setup

$$\mathbf{T} \cdot \mathbf{P} \cdot \mathbf{S} \cdot \mathbf{M}_l^{-1} \cdot \begin{bmatrix} R_x \\ R_y \\ R_z \\ 1 \end{bmatrix} = \begin{bmatrix} s \\ t \\ 1 \\ 1 \end{bmatrix}$$

\mathbf{M}_l^{-1} is linear part of the
affine modelview transformation

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Texture Matrix Sub-parts

$$\mathbf{P} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

\mathbf{P} is projective transform that divides
by the z component

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Texture Matrix Sub-parts (2)

$$S = \begin{bmatrix} -1 & 0 & 0 & dx \\ 0 & -1 & 0 & dy \\ 0 & 0 & 1 & dz \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

**S subtracts object-space reflection vector
from each paraboloid's orientation, d
d is either [0, 0, -1] or [0, 0, 1]**

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Texture Matrix Sub-parts (3)

$$T = \begin{bmatrix} .5 & 0 & 0 & .5 \\ 0 & .5 & 0 & .5 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

**T maps [-1, 1] vector space range
into [0, 1] texture space range**

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Reflection Vector Tex Coords

- Texture matrix assumes **glTexCoor3f** used to pass in eye-space reflection vector
- Alternative is to use NV_reflection_vector OpenGL extension
 - Special texture coordinate generation mode
 - Supported by RIVA TNT OpenGL and Mesa 3.1
 - GL_REFLECTION_MAP_NV generates eye-space reflection vector
 - GL_NORMAL_MAP_NV generates eye-space normal vector

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Extension Usage

- Reflection map usage

```
mapMode = GL_REFLECTION_MAP_NV;  
glTexGeni(GL_S, GL_TEXTURE_GEN_MODE, mapMode);  
glTexGeni(GL_T, GL_TEXTURE_GEN_MODE, mapMode);  
glTexGeni(GL_R, GL_TEXTURE_GEN_MODE, mapMode);
```

- Normal map usage

```
mapMode = GL_NORMAL_MAP_NV;  
glTexGeni(GL_S, GL_TEXTURE_GEN_MODE, mapMode);  
glTexGeni(GL_T, GL_TEXTURE_GEN_MODE, mapMode);  
glTexGeni(GL_R, GL_TEXTURE_GEN_MODE, mapMode);
```

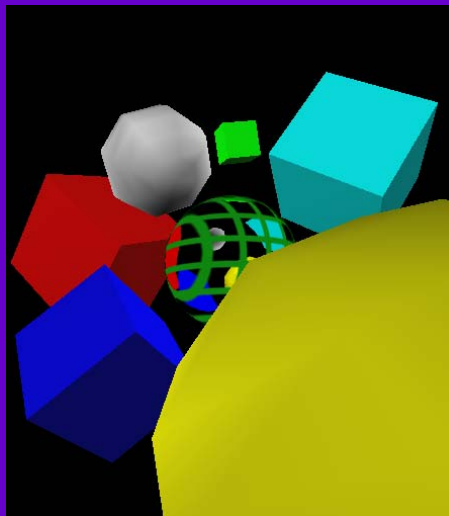
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Extension Enumerant Values

- #define GL_NORMAL_MAP_NV 0x8511
- #define GL_REFLECTION_MAP_NV 0x8512

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Example Scene



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Basis for Per-pixel Lighting

- Encode the specular directional light contributions in the scene as two dual paraboloid maps; use with reflection vector
- Encode the diffuse directional light contributions for the scene in another set of maps; use with normal vector
- Two multi-textured passes gives per-pixel specular and diffuse lighting

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Dual-parabolic Mapping Math

How to map (r_x, r_y, r_z) unit vector to (s, t) texture coordinate in $[-1, 1]$ range.

front

$$s = r_x / (1 - r_z)$$

$$t = r_y / (1 - r_z)$$

back

$$s = -r_x / (r_z + 1)$$

$$t = -r_y / (r_z + 1)$$

Reverse mapping: (s, t) to (r_x, r_y, r_z)

front

$$r_x = 2s / (s^2 + t^2 + 1)$$

$$r_y = 2t / (s^2 + t^2 + 1)$$

$$r_z = (-1 + s^2 + t^2) / (s^2 + t^2 + 1)$$

back

$$r_x = -2s / (s^2 + t^2 + 1)$$

$$r_y = -2t / (s^2 + t^2 + 1)$$

$$r_z = -(-1 + s^2 + t^2) / (s^2 + t^2 + 1)$$

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References

- Heidrich & Seidel, “View-independent Environment Maps” *Eurographics Workshop on Graphics Hardware*, 1998.
- Background: Doug Voorhies & Jim Foran, “Reflection vector shading hardware,” *SIGGRAPH '94 Proceedings*, 1994.