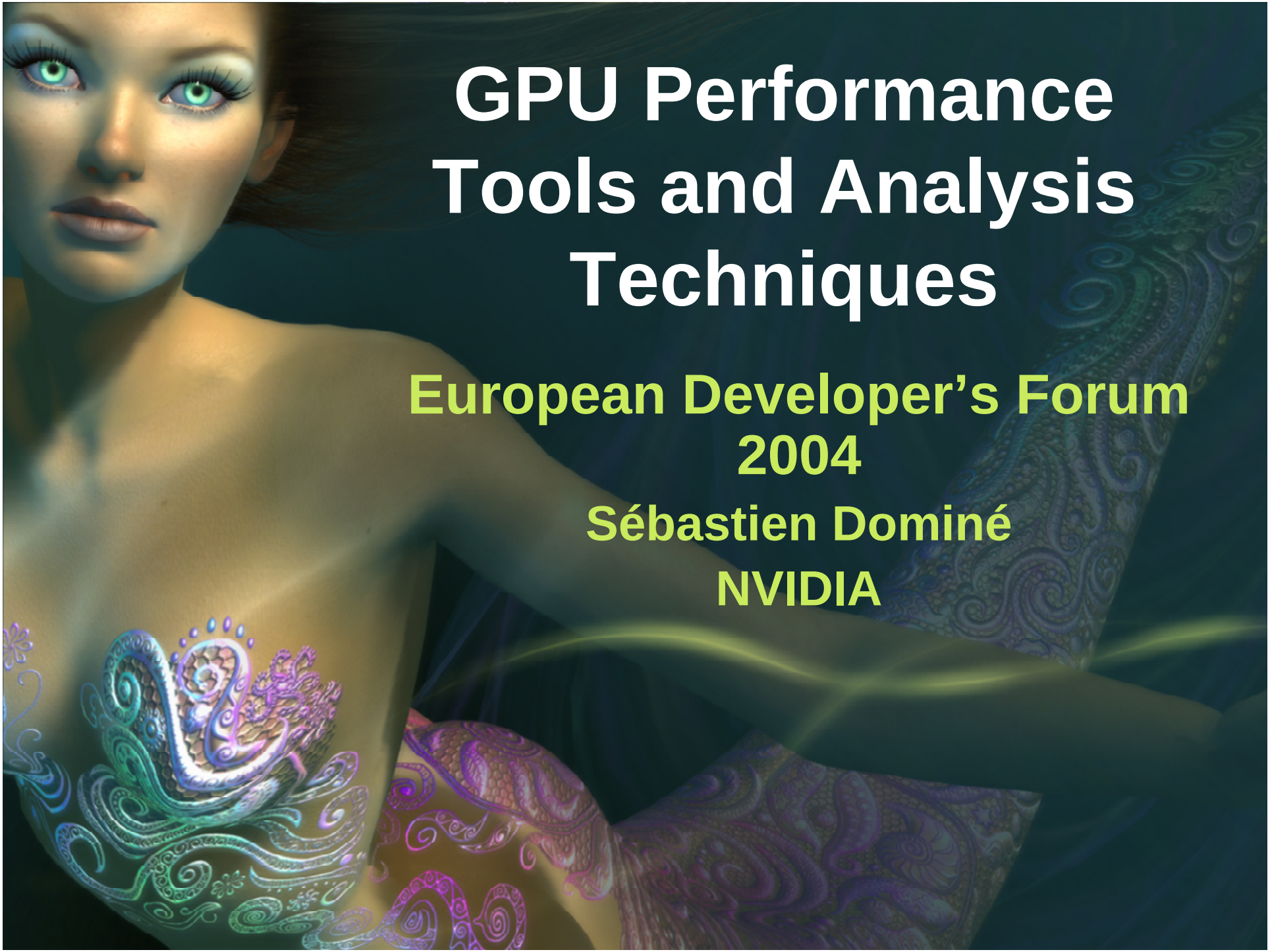

GPU Performance Tools and Analysis Techniques

European Developer's Forum 2004

Sébastien Dominé

NVIDIA

Agenda

- Performance Tools Survey
- Practice
- Next generation Performance Tools
- Conclusion
- Q & A

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Performance Tools Survey

- NVPerfHUD
  - Direct3D9 Performance HUD
- NVShaderPerf
  - Offline Shader Performance Analysis
- FX Composer
  - HLSL Shader Editor IDE

NVPerfHUD 2.0

- Overlay graph that displays stats from :
  - Direct3D9 API interception layer
  - Direct3D Driver
  - Requires NVIDIA GPU
- Able to bypass and inject API calls to assist with performance analysis
- Only works on your own application

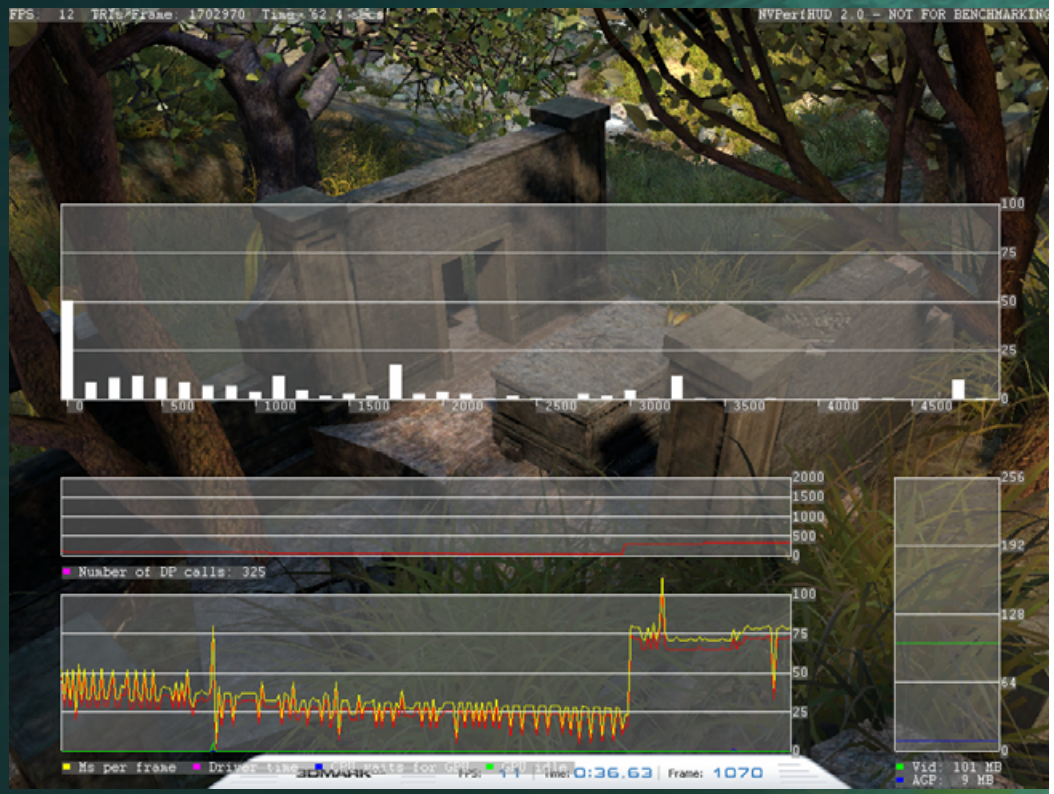


Image courtesy of FutureMark Corp.

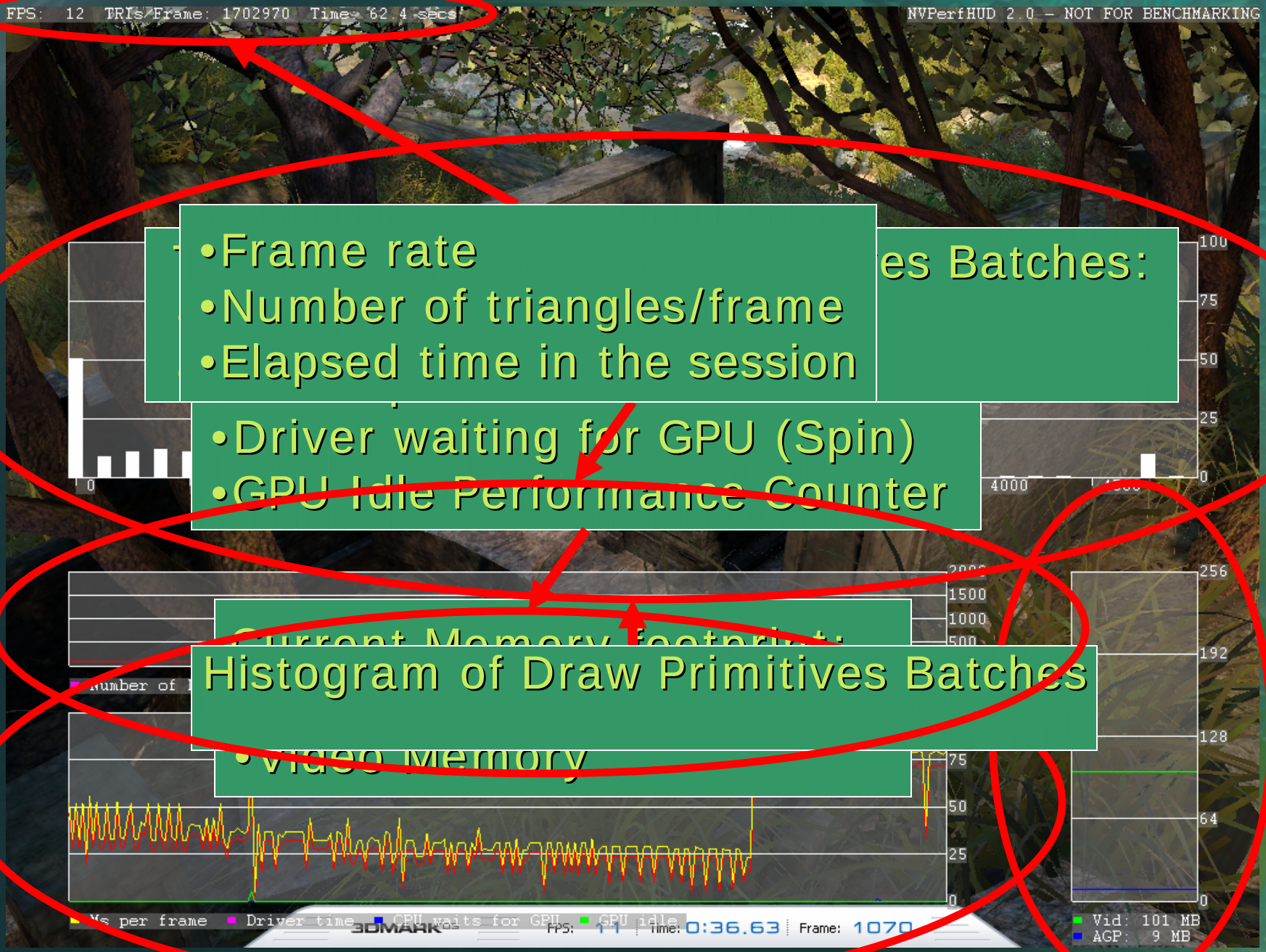
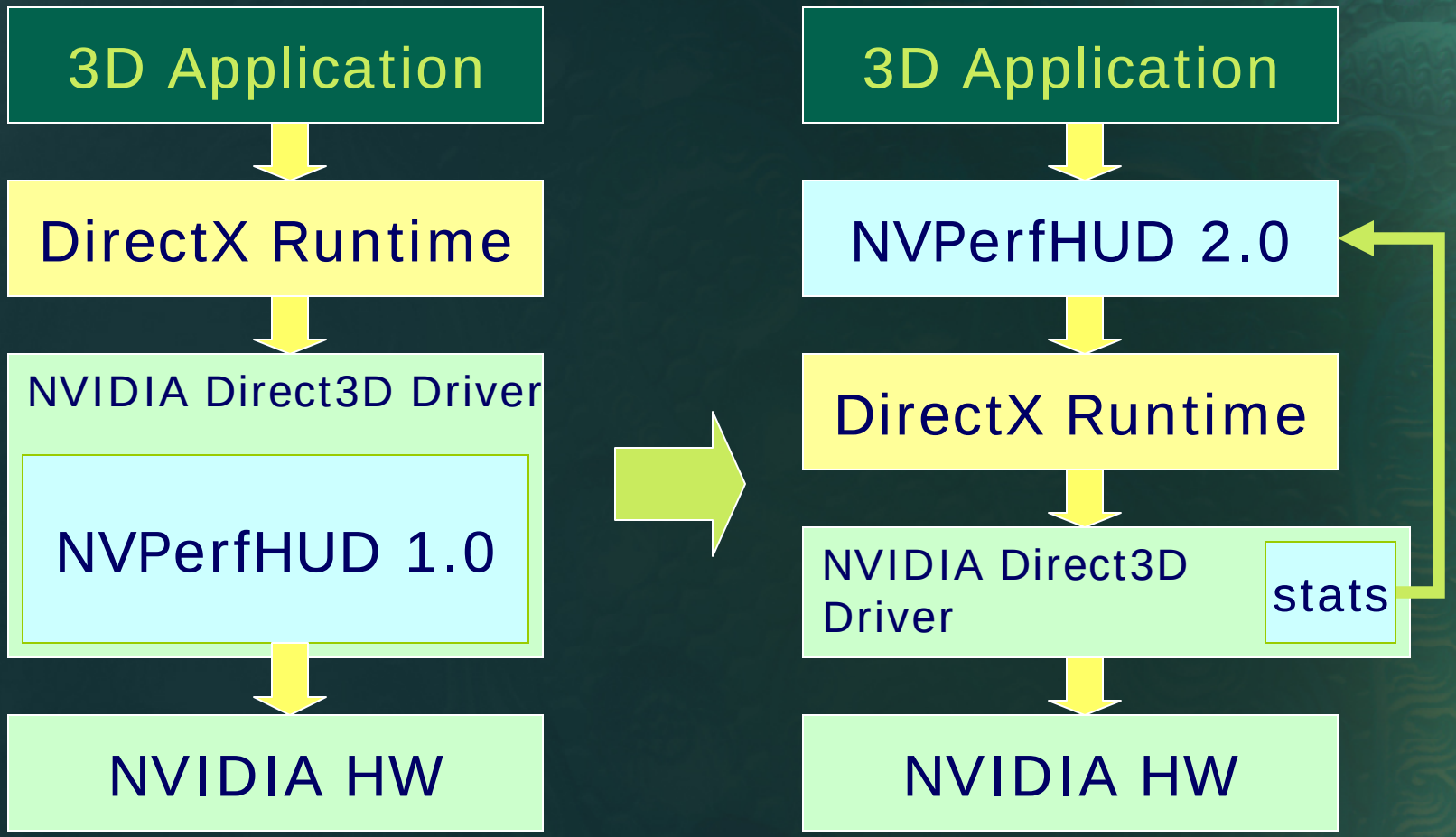
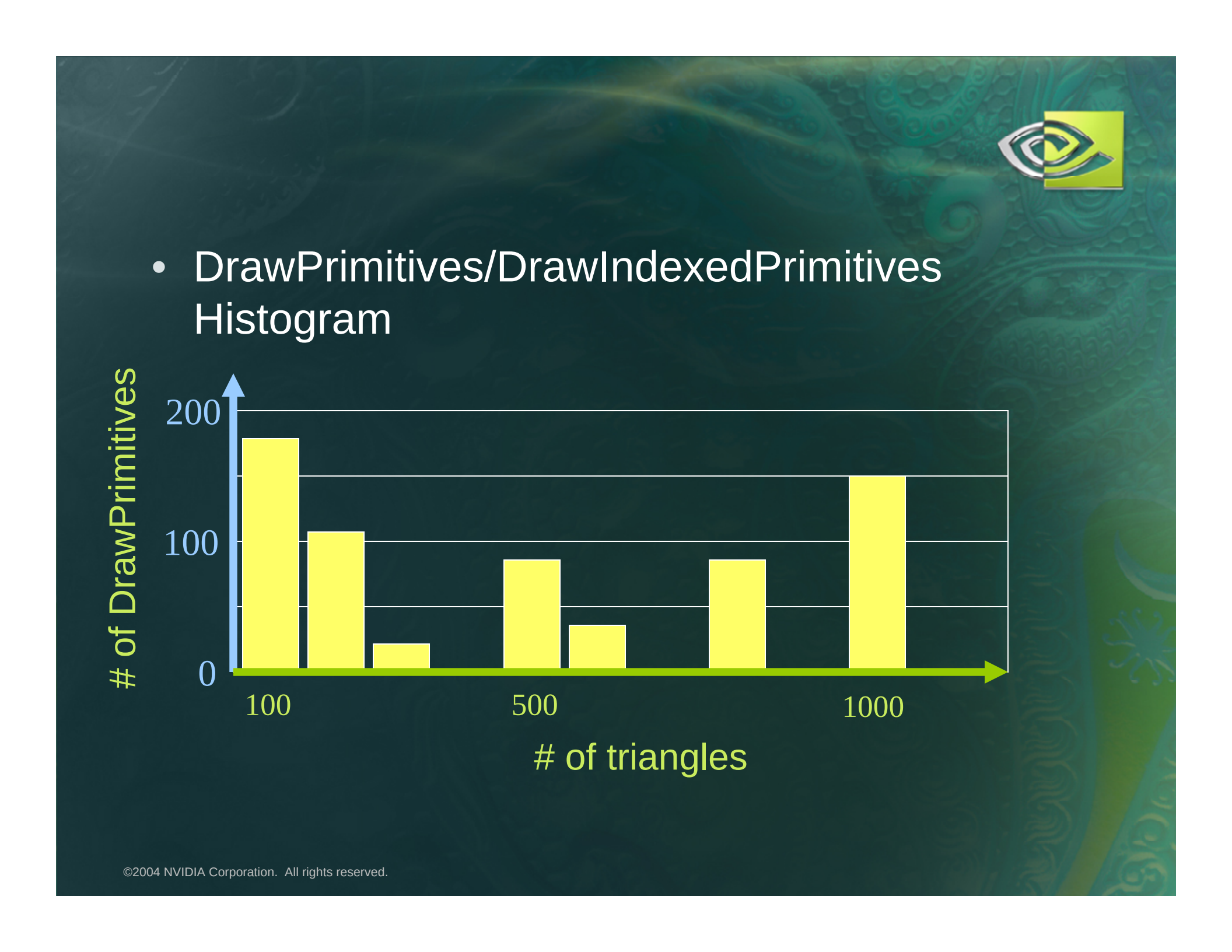


Image courtesy of FutureMark Corp.

What's new in 2.0?





- DrawPrimitives/DrawIndexedPrimitives Histogram

Texture Stage States

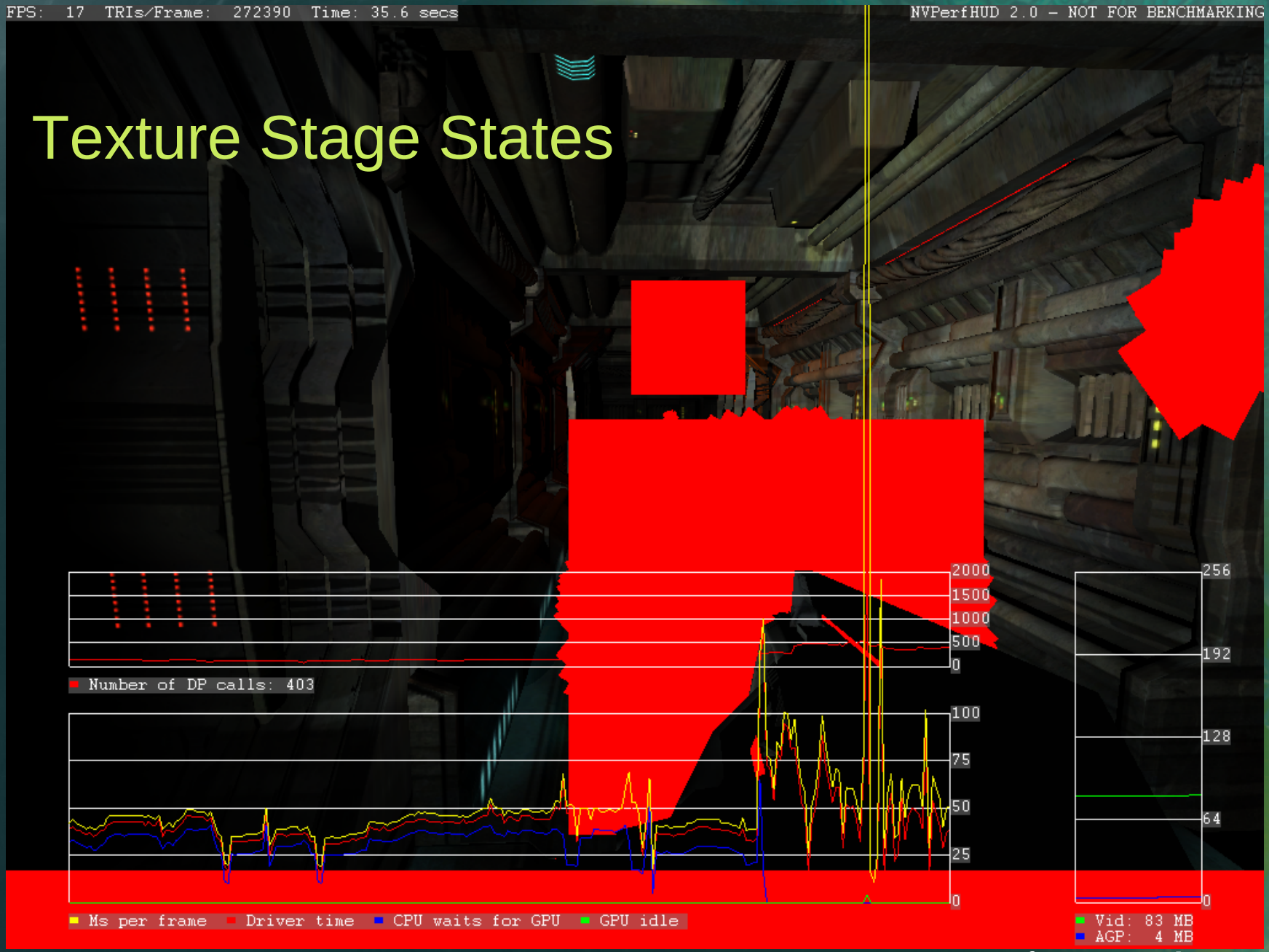


Image courtesy of FutureMark Corp.

Pixel Shaders 1.x

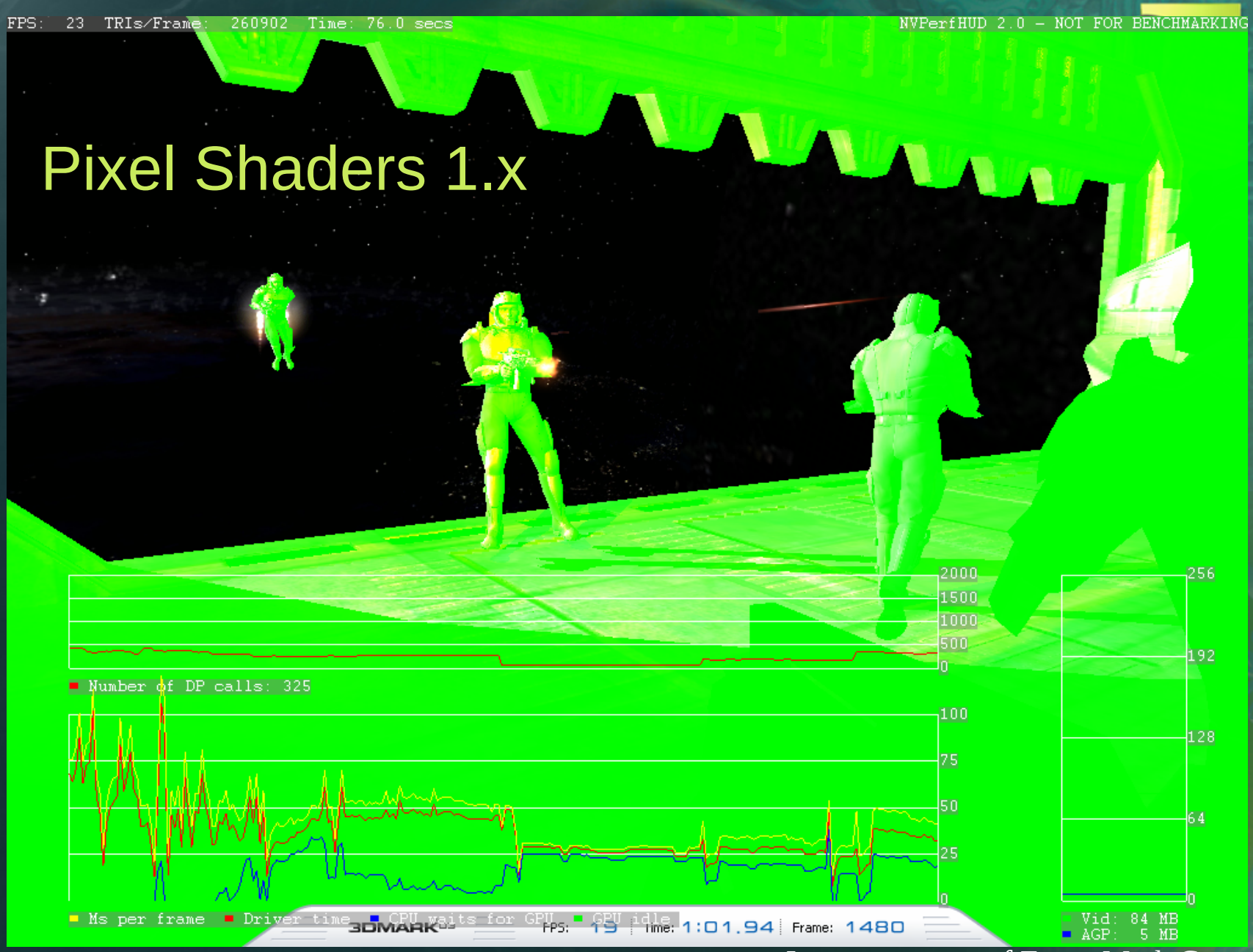


Image courtesy of FutureMark Corp.

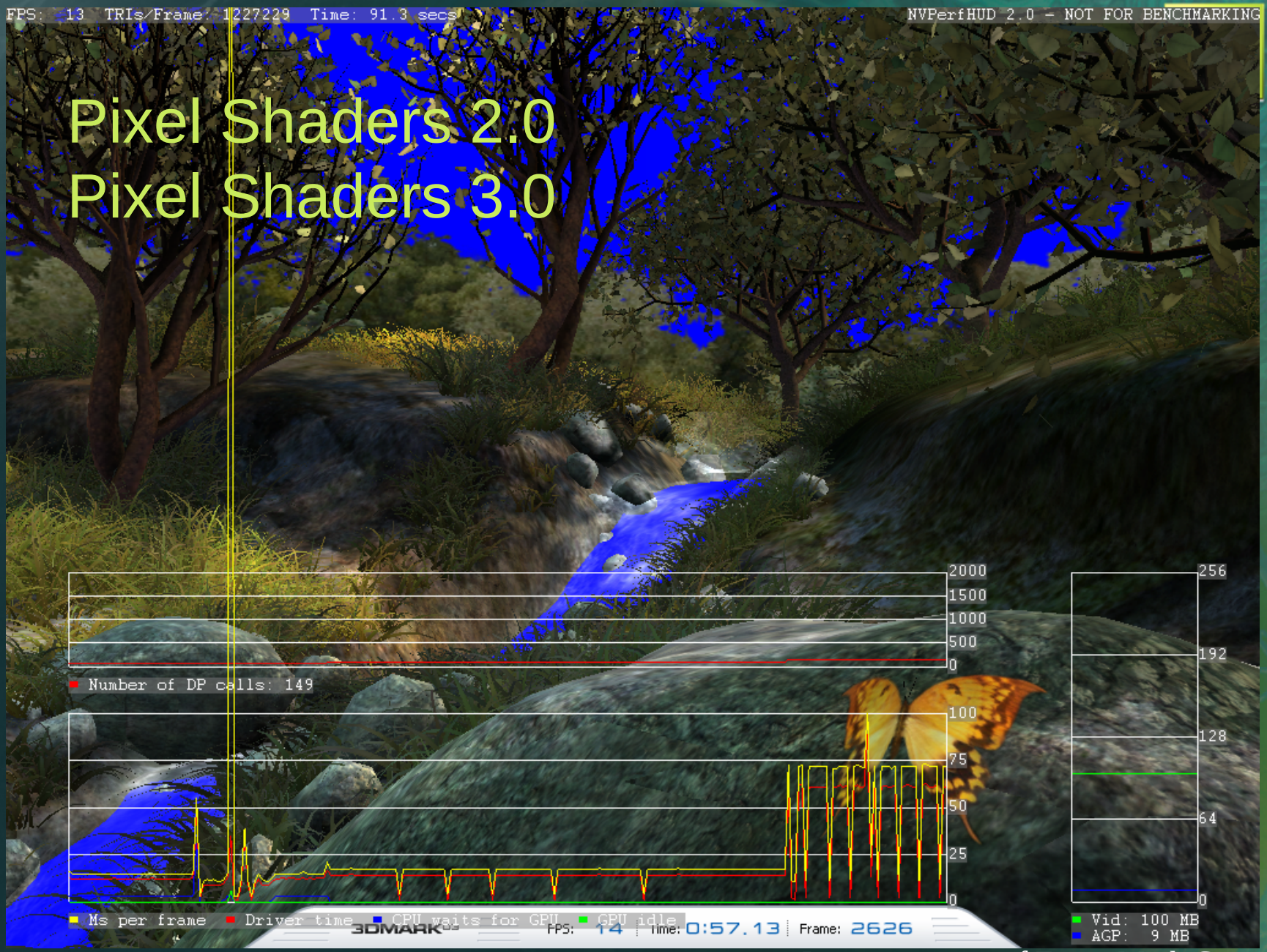


Image courtesy of FutureMark Corp.

2x2 Texture replacement

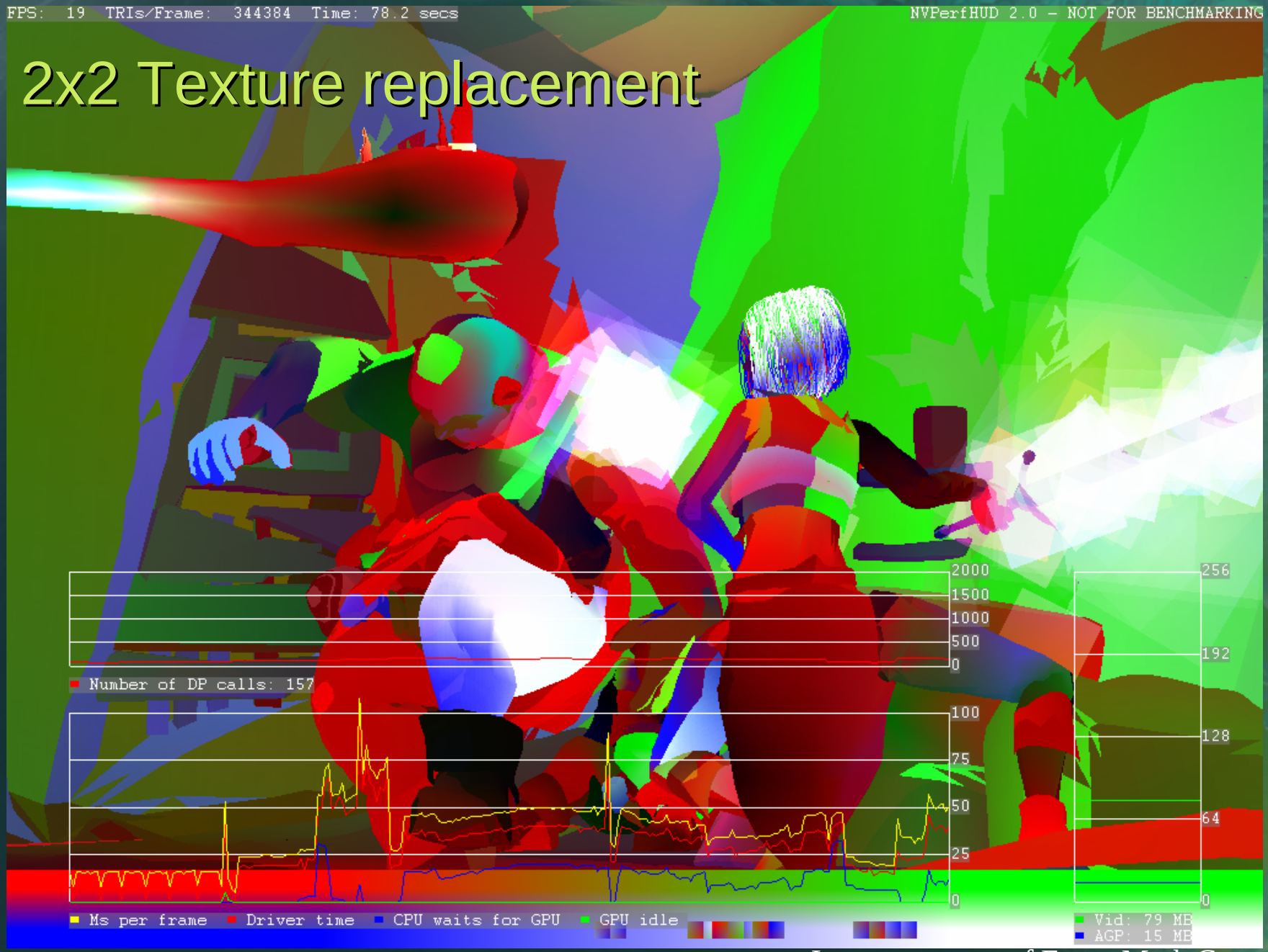


Image courtesy of FutureMark Corp.

- Null DrawPrimitive mode
- Null Viewport mode

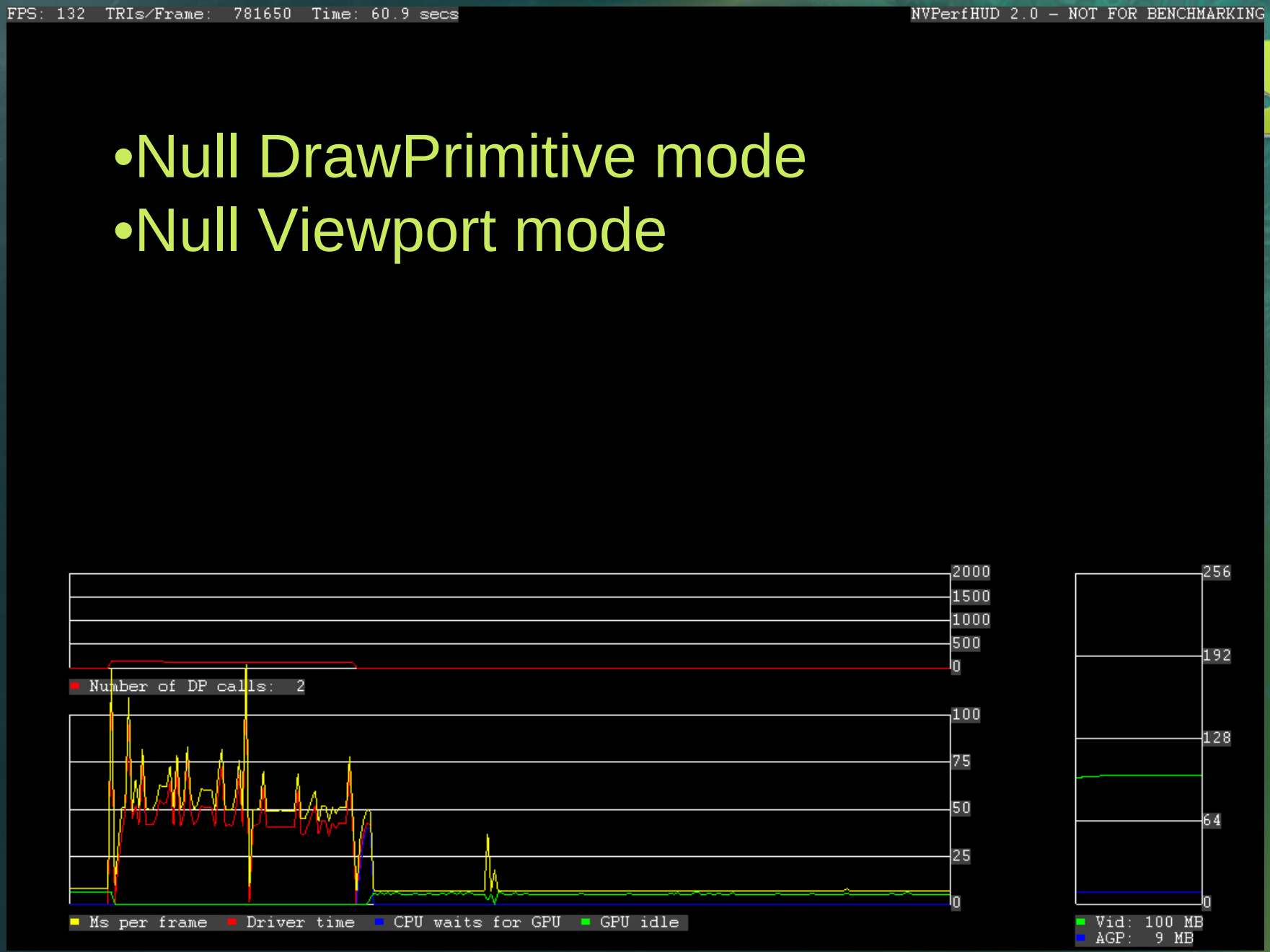


Image courtesy of FutureMark Corp.

NVPerfHUD - Overhead

- NVPerfHUD is fairly lean but...
- Overlay graph and DLL interception can costs up to 1.3%
- Driver instrumentation can cost up to 6%
- Upper bound for total cost: 7%

NVShaderPerf

```
v2f BumpReflectVS(a2v IN,
                  uniform float4x4 WorldViewProj,
                  uniform float4x4 World,
                  uniform float4x4 ViewIT)
{
    v2f OUT;
    // Position in screen space.
    OUT.Position = mul(IN.Position, WorldViewProj);
    // Pass texture coordinates for fetching the normal map
    OUT.TexCoord.xy = IN.TexCoord;
    OUT.TexCoord.w = 1.0;
    // compute the 4x4 tranform from tangent space to object space
    float3x3 TangentToObjSpace;
    // first rows are the tangent and binormal scaled by the bump scale
    TangentToObjSpace[0] = float3(IN.Tangent.x, IN.Binormal.x, IN.Normal.x);
    TangentToObjSpace[1] = float3(IN.Tangent.y, IN.Binormal.y, IN.Normal.y);
    TangentToObjSpace[2] = float3(IN.Tangent.z, IN.Binormal.z, IN.Normal.z);
    OUT.TexCoord1.x = dot(World[0].xyz, TangentToObjSpace[0]);
                                                    n cube space
                                                    ose contains eye position
}
////
float
    uniform float BumpS      ) : COLOR
{
    // fetch the bump n      l from th
    float3 normal = tex      map
    normal = normalize(      )
    // transform the bu      ma
    // then use the tra      rmed nor
    // used to fetch th      be map
    // (we multiply by      ly to increase brightness)
                                                    d3.w);
}
```

Inputs:
- HLSL
- PS1.x,PS2.x,PS3.x
- VS1.x,VS2.x, VS3.x

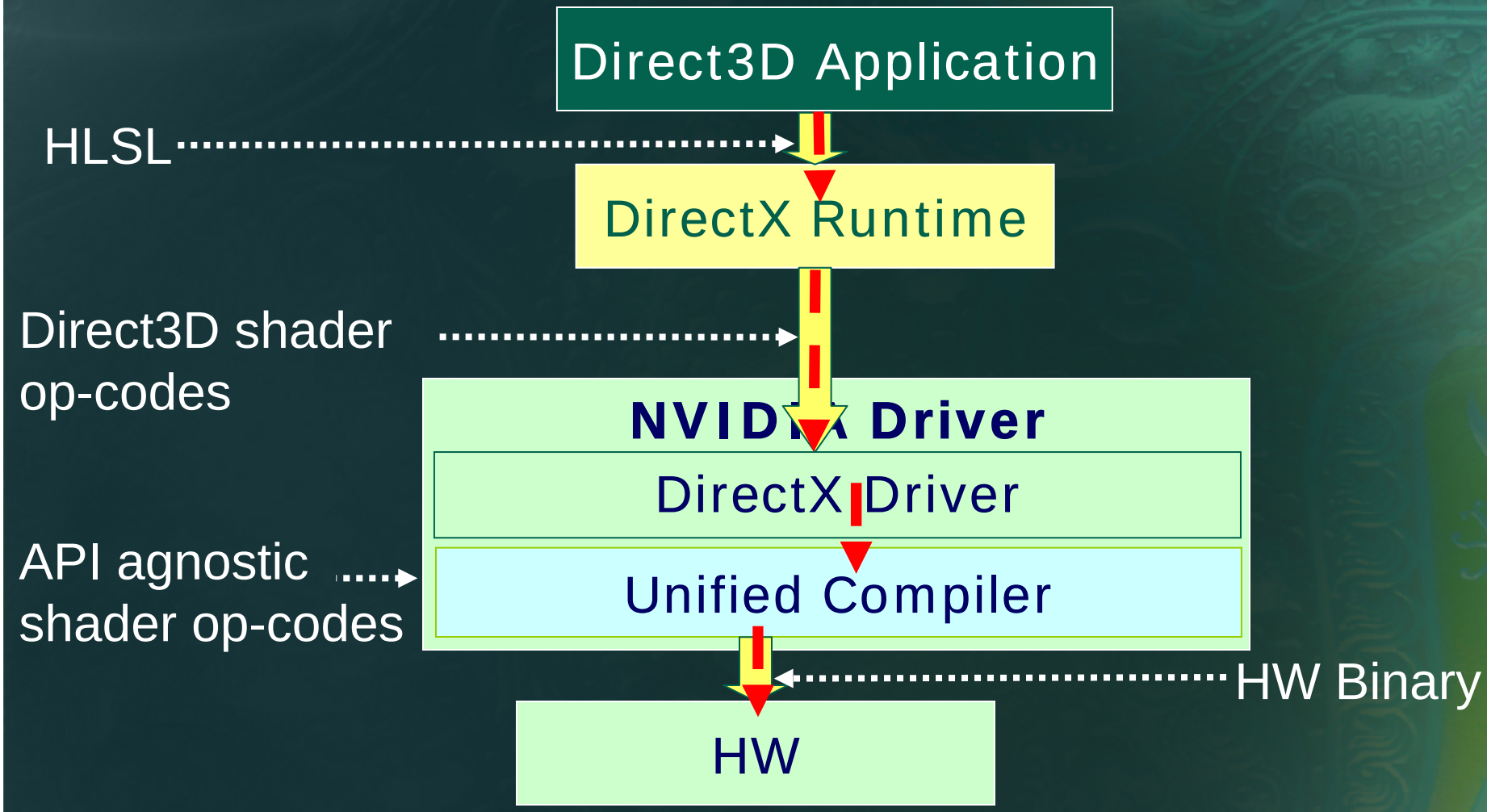
GPU Arch:
- GeForce FX (NV3X)
- GeForce 6 Series (NV4X)
- Quadro FX (NV3X+NV4X)

NVShaderPerf

```
C:\WINDOWS\system32\cmd.exe
    dp3 r0.x, r1, r1
    rsq r0.w, r0.x
    nrm r0.xyz, t1
    mad r1.xyz, r1, r0.w, r0
    nrm r2.xyz, r1
    nrm r1.xyz, t2
    dp3 r2.x, r2, r1
    max r1.w, r2.x, c9.x
    pow r0.w, r1.w, c5.x
    add r1.w, r0.w, -c7.x
    mov r2.w, c6.x
    add r2.w, r2.w, -c7.x
    rcp r2.w, r2.w
    mul_sat r2.w, r1.w, r2.w
    mad r1.w, r2.w, c9.y, c9.z
    mul r2.w, r2.w, r2.w
    mul r1.w, r1.w, r2.w
    mov r2.x, c9.w
    add r2.w, r2.x, -c8.x
    mad r1.w, r1.w, r2.w, c8.x
    dp3 r0.x, r0, r1
    mul r0.w, r0.w, r1.w
    mul r1.xyz, r0.w, c4
Cycles: 21.00 :: R Regs Used: 3 :: R Regs Max Index (0 based
Pixel throughput (assuming 1 cycle texture lookup) 304.76 M

C:\Temp\NVShaderPerf_61_77>
```

Outputs:
- Assembly code
- # of cycles
- # of temporary registers
- Pixel throughput
- Forces all fp16 and all fp32 (gives performance bounds)

NVShaderPerf



NVShaderPerf - Example

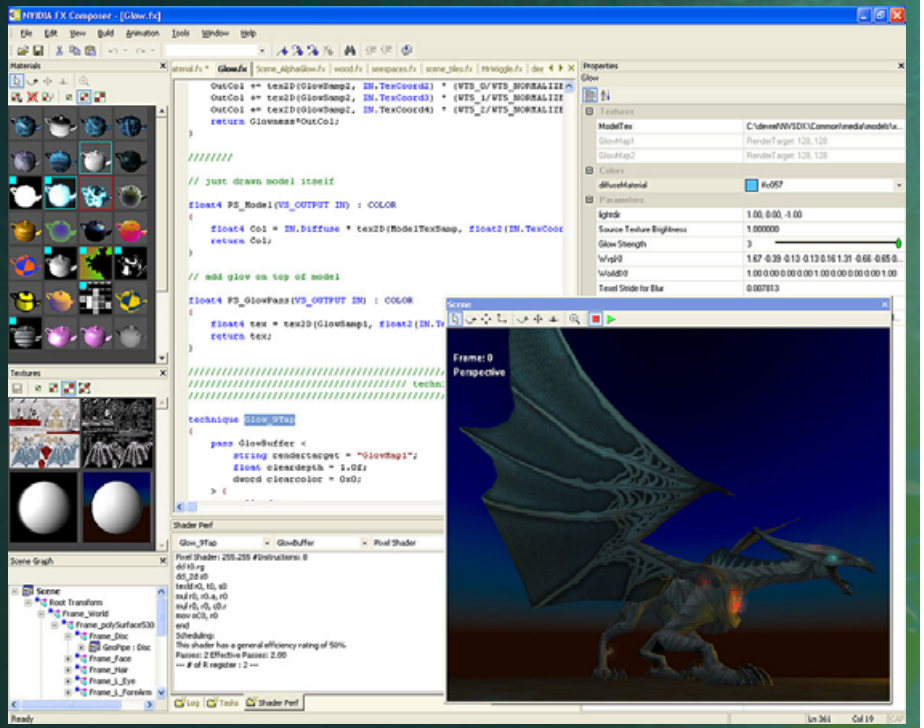
```
v2f BumpReflectVS(a2v IN,
                  uniform float4x4 WorldViewProj,
                  uniform float4x4 World,
                  uniform float4x4 ViewIT)
{
    v2f OUT;
    // Position in screen space.
    OUT.Position = mul(IN.Position, WorldViewProj);
    // Pass texture coordinates through unmodified
    OUT.TexCoord = IN.TexCoord;
    OUT.TexCoord.w = 1.0;
    // compute the 4x4 tranform from tangent space to object space
    float3x3 TangentToObjSpace;
    // first rows are the tangent and binormal scaled by the bump scale
    TangentToObjSpace[0] = float3(IN.T
    TangentToObjSpace[1] = float3(IN.T
    TangentToObjSpace[2] = float3(IN.T
    OUT.TexCoord1.x = dot(World[0].xyz
    OUT.TexCoord1.y = dot(World[1].xyz
    OUT.TexCoord1.z = dot(World[2].xyz
    OUT.TexCoord2.x = dot(World[0].xyz
    OUT.TexCoord2.y = dot(World[1].xyz
    OUT.TexCoord2.z = dot(World[2].xyz
    OUT.TexCoord3.x = dot(World[0].xyz
    OUT.TexCoord3.y = dot(World[1].xyz
    OUT.TexCoord3.z = dot(World[2].xyz
    float4 worldPos = mul(IN.Position,
    // compute the eye vector (going f
    float4 eyeVector = worldPos - View
    OUT.TexCoord1.w = eyeVector.x;
    OUT.TexCoord2.w = eyeVector.y;
    OUT.TexCoord3.w = eyeVector.z;
}
////
float
{
}
```

```
C:\WINDOWS\system32\cmd.exe
C:\Temp\NVShaderPerf_61_77>NVShaderPerf.exe -a nv40 -allprec -v 0 goochy_HLSL.fx

--------------------------------------------------------------------------------

Running performance on file goochy_HLSL.fx
********************************************************************************
Technique <Untextured>, Pass <p0>
-------------------- NV40 --------------------
Target: GeForce 6800 Ultra (NV40) :: Unified Compiler: v61.77
Cycles: 21.00 :: R Regs Used: 3 :: R Regs Max Index (0 based): 2
Pixel throughput (assuming 1 cycle texture lookup) 304.76 MP/s
================================================================================

Shader performance using all FP16
Cycles: 14.00 :: R Regs Used: 2 :: R Regs Max Index (0 based): 1
Pixel throughput (assuming 1 cycle texture lookup) 457.14 MP/s
================================================================================

Shader performance using all FP32
Cycles: 21.00 :: R Regs Used: 3 :: R Regs Max Index (0 based): 2
Pixel throughput (assuming 1 cycle texture lookup) 304.76 MP/s

C:\Temp\NVShaderPerf_61_77>
```

```
C:\WINDOWS\system32\cmd
C:\Temp\NVShaderPerf_61_7

--------------------------

Running performance on f
**************************
Technique <Untextured>, Pass <p0>
-------------------- NV34 --------------------
Target: GeForceFX 5200 Ultra (NV34) :: Unified Compiler: v61.77
Cycles: 51 :: # R Registers: 4
Pixel throughput (assuming 1 cycle texture lookup) 15.69 MP/s
================================================================================

Shader performance using all FP16
Cycles: 51 :: # R Registers: 2
Pixel throughput (assuming 1 cycle texture lookup) 15.69 MP/s
================================================================================

Shader performance using all FP32
Cycles: 51 :: # R Registers: 4
Pixel throughput (assuming 1 cycle texture lookup) 15.69 MP/s

C:\Temp\NVShaderPerf_61_77>_
```

FX Composer 1.5

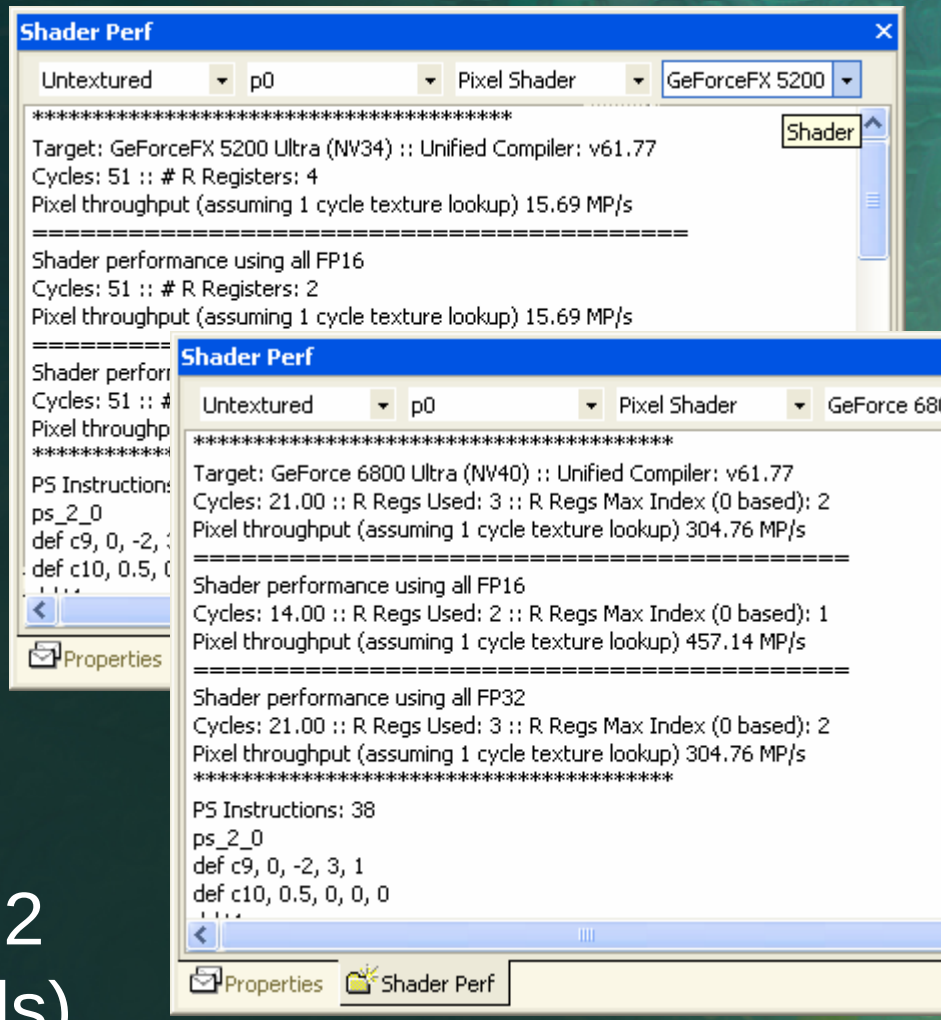
- IDE for HLSL authoring, debugging and optimization
- Vertex and Pixel Shader scheduling
- Direct3D9 VS/PS op-code disassembly
- Advanced texture generation for baking Look Up Tables
- Visualization of RenderTargets



EverQuest® content courtesy Sony Online Entertainment

FX Composer – Shader Perf

- Disassembly
- Target GPU
- Driver version match
- Number of Cycles
- Number of Registers
- Pixel Throughput
- Forces all fp16 and all fp32 (gives performance bounds)



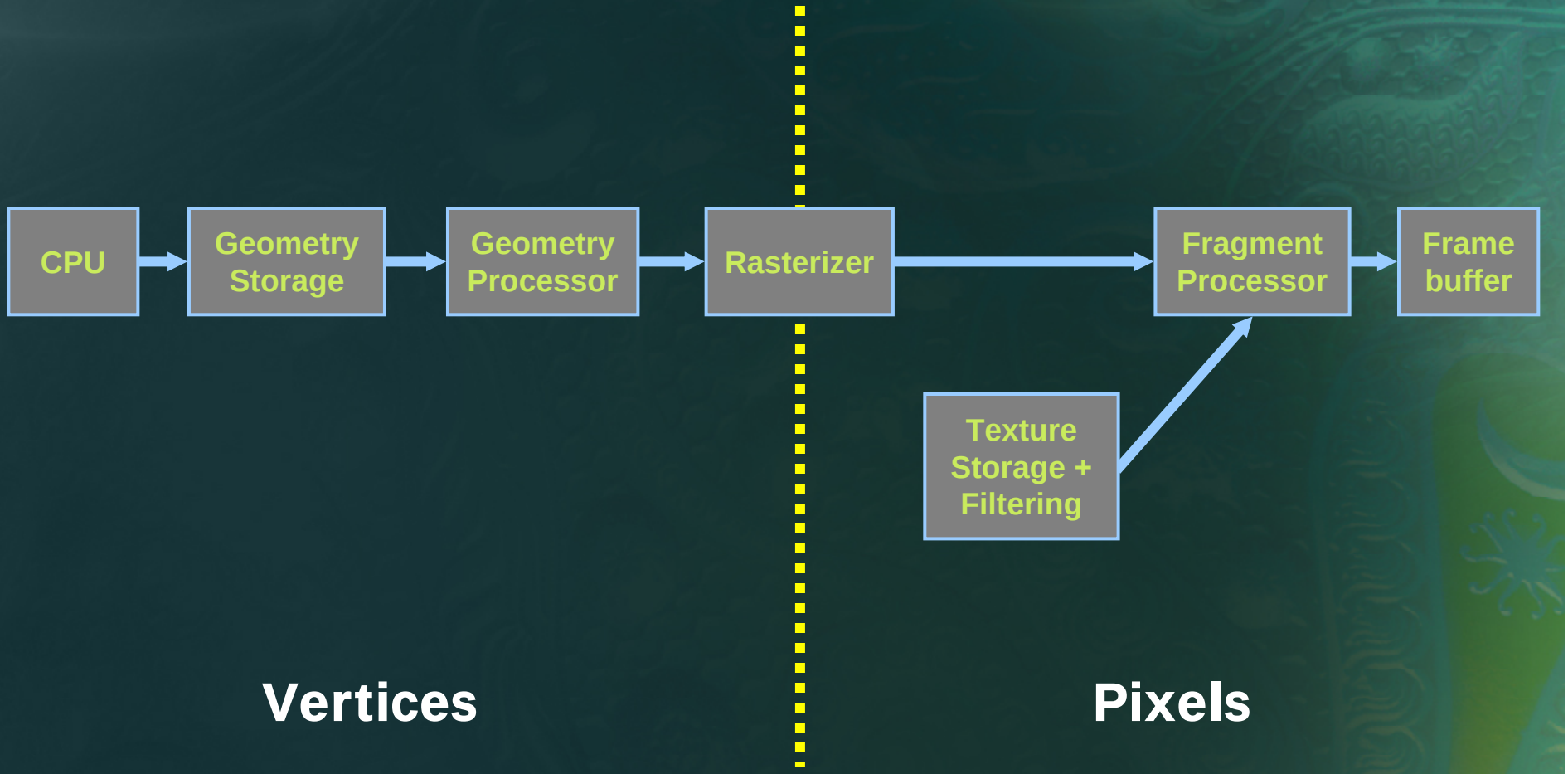
Agenda

- Performance Tools Survey
- Practice
- Next generation Performance Tools
- Conclusion
- Q & A

Basic Principles

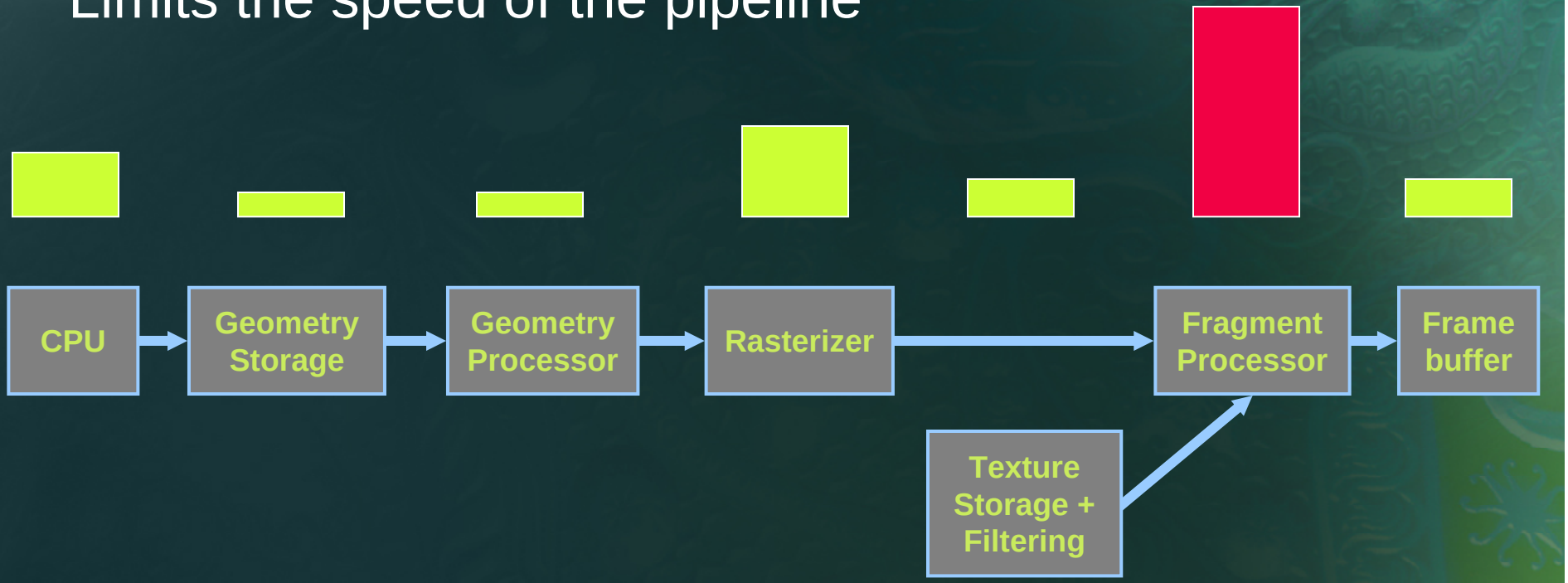
- Pipelined architecture
  - Each part needs the data from the previous part to do its job
- Bottleneck identification and elimination
- Balancing the pipeline

Pipelined Architecture (simplified view)



The Terrible Bottleneck

Limits the speed of the pipeline

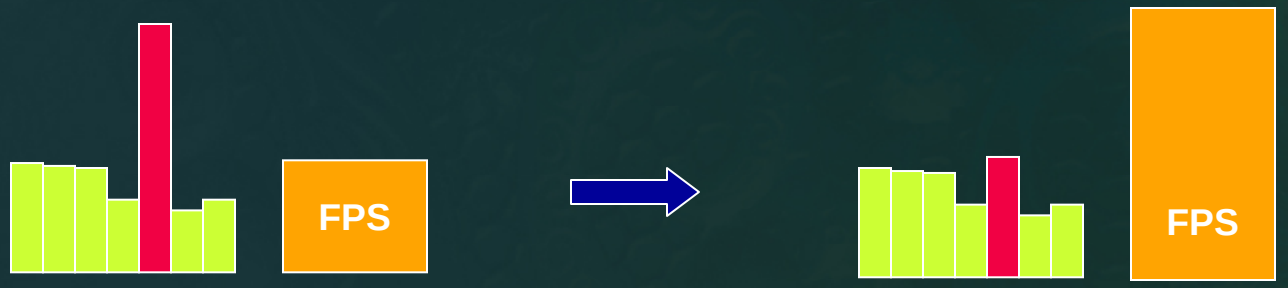


Bottleneck Identification

- Need to identify it quickly and correctly
  - Guessing what it is without testing can waste a lot of coding time
- Two ways to identify a stage as the bottleneck
  - Modify the stage itself
  - Rule out the other stages

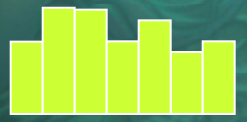
Bottleneck Identification

- Modify the stage itself
  - By decreasing its workload

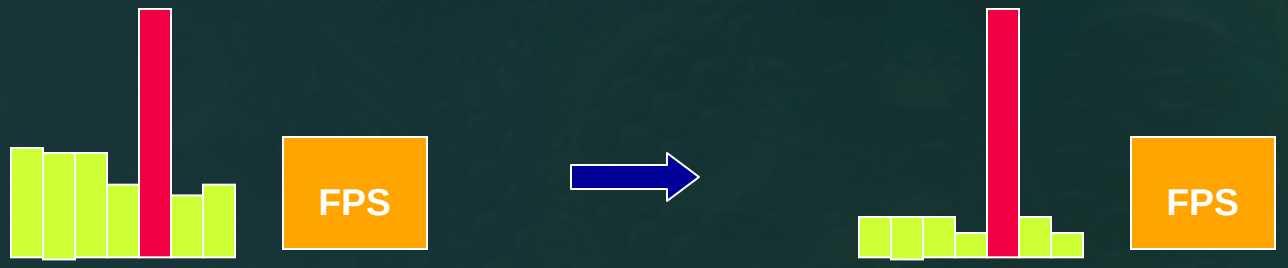


  - If performance improves greatly, then you know this is the bottleneck
  - Careful not to change the workload of other stages!

Bottleneck Identification



- Rule out the other stages
  - By giving all of them little or no work



  - If performance doesn't change significantly, then you know this is the bottleneck
  - Careful not to change the workload of this stage!

Practice

- Now lets look at some sample problems and see if we can find out where the problem is
- Use NVPerfHUD to help

Practice: Example 1

- A seemingly simple scene runs horribly slow
  - Narrow in on the bottleneck

Practice: Example 1

- Dynamic vertex buffer
  - BAD creation flags

```
HRESULT hr = pd3dDevice->CreateVertexBuffer(
                        6* sizeof( PARTICLE_VERT ),
                        0,      //declares this as static
                        PARTICLE_VERT::FVF,
                        D3DPOOL_DEFAULT,
                        &m_pVB,
                        NULL );
```

Practice: Example 1

- Dynamic vertex buffer
  - GOOD creation flags

```
HRESULT hr = pd3dDevice->CreateVertexBuffer(
                        6* sizeof( PARTICLE_VERT ),
                        D3DUSAGE_DYNAMIC |
                        D3DUSAGE_WRITEONLY,
                        PARTICLE_VERT::FVF,
                        D3DPOOL_DEFAULT,
                        &m_pVB,
                        NULL );
```

Practice: Example 1

- Dynamic Vertex Buffer
  - BAD Lock flags

```
m_pVB->Lock(0, 0,(void**)&quadTris, 0);
```

- No flags at all!?
  - That can’t be good....

Practice: Example 1

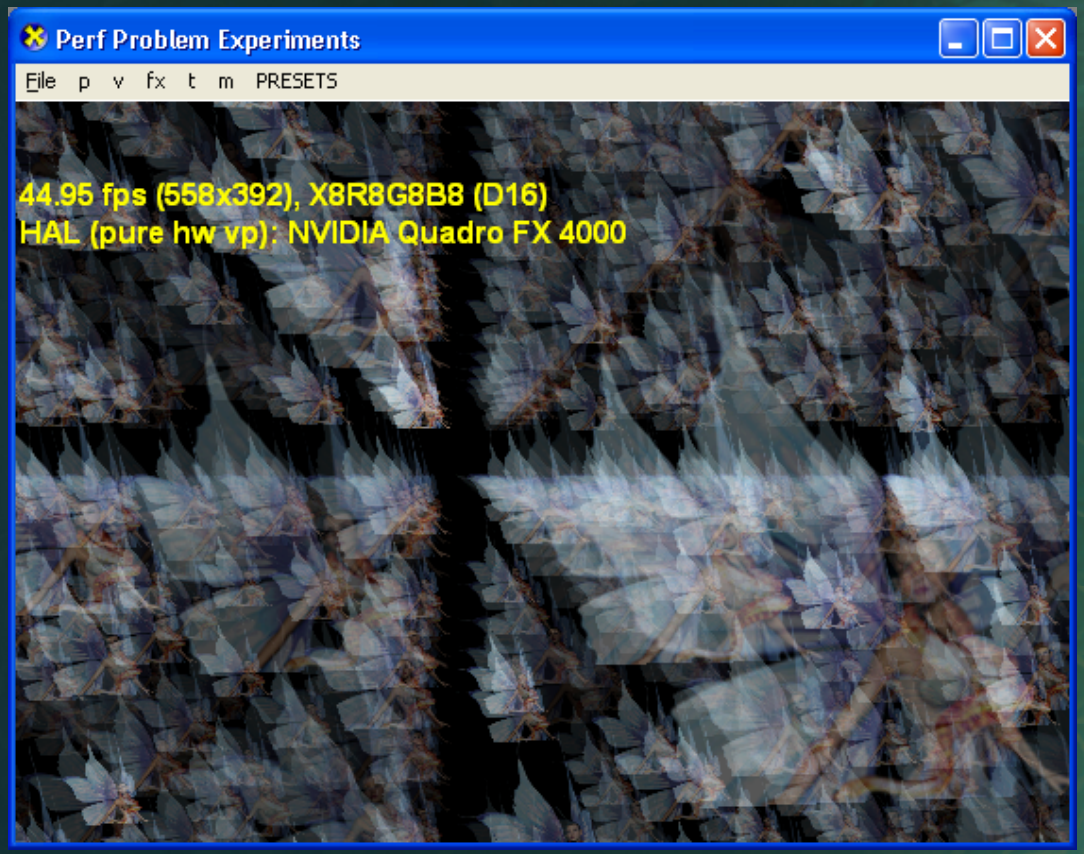
- Dynamic Vertex Buffer
  - GOOD Lock flags

```
m_pVB->Lock(0, 0,(void**)&quadTris,
D3DLOCK_NOSYSLOCK | D3DLOCK_DISCARD);
```

- Use D3DLOCK_DISCARD the first time you lock a vertex buffer each frame
  - And again when that buffer is full
  - Otherwise just use NOSYSLOCK

Practice: Example 2

- Another slow scene
  - What's the problem here

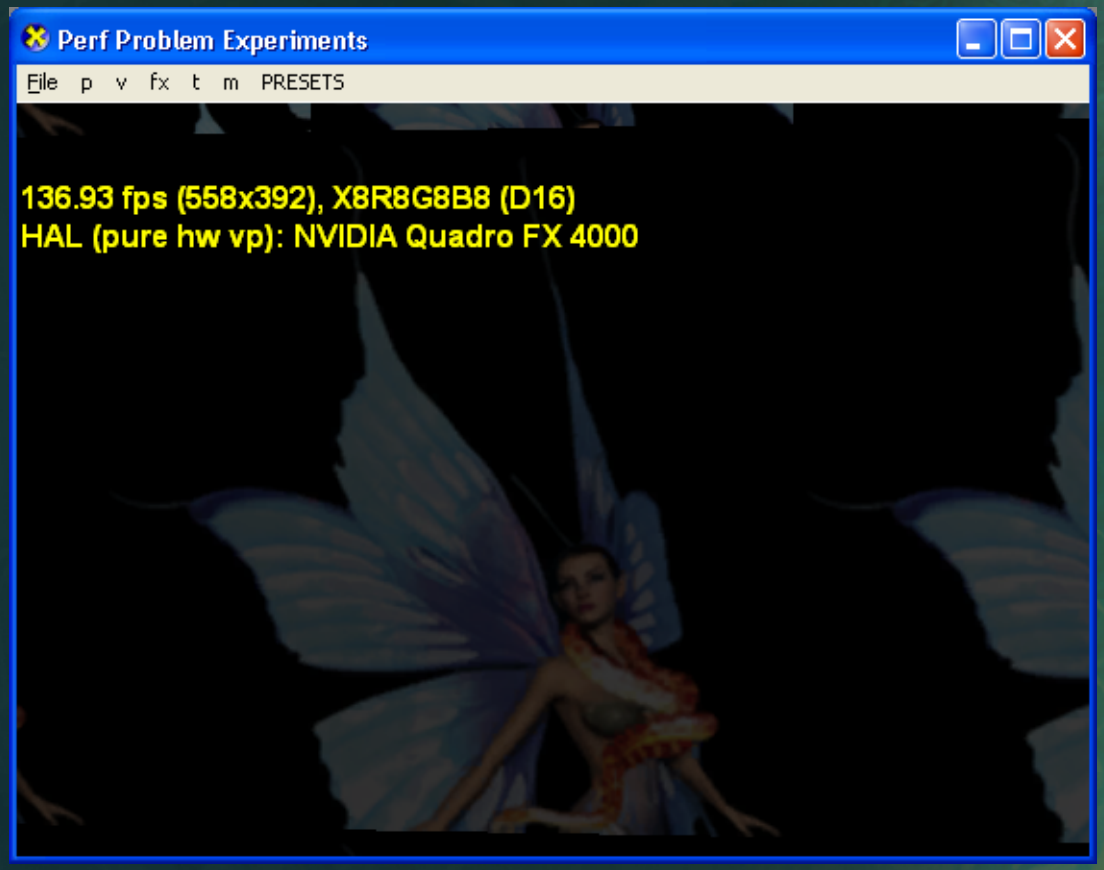


Practice: Example 2

- Texture bandwidth overkill
  - Use mipmaps
  - Use dxt1 if possible
    - Some cards can store compressed data in cache
  - Use smaller textures when they are fine
    - Does the grass blade really need a 1024x1024 texture?
      - Maybe

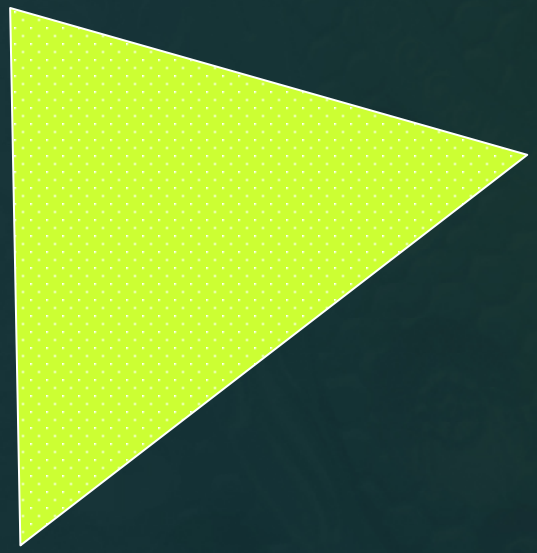
Practice: Example 3

- Another slow scene
  - Who wants a prize?



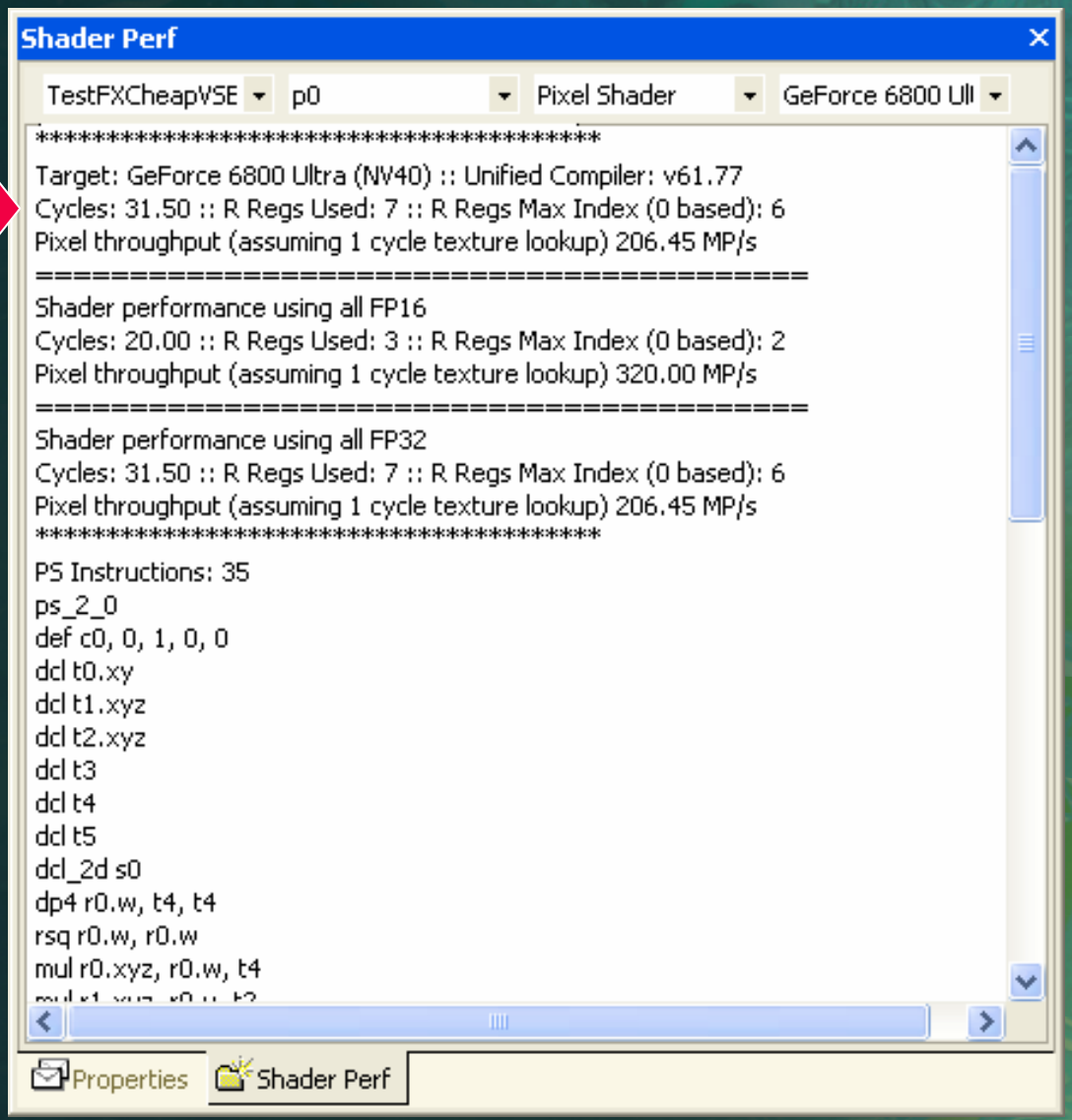
Practice: Example 3

- Expensive pixel shader
  - Can have huge performance effect
  - Only 3 verts, but maybe a million pixels
    - That’s only 1024x1024



Look at all the pixels!!

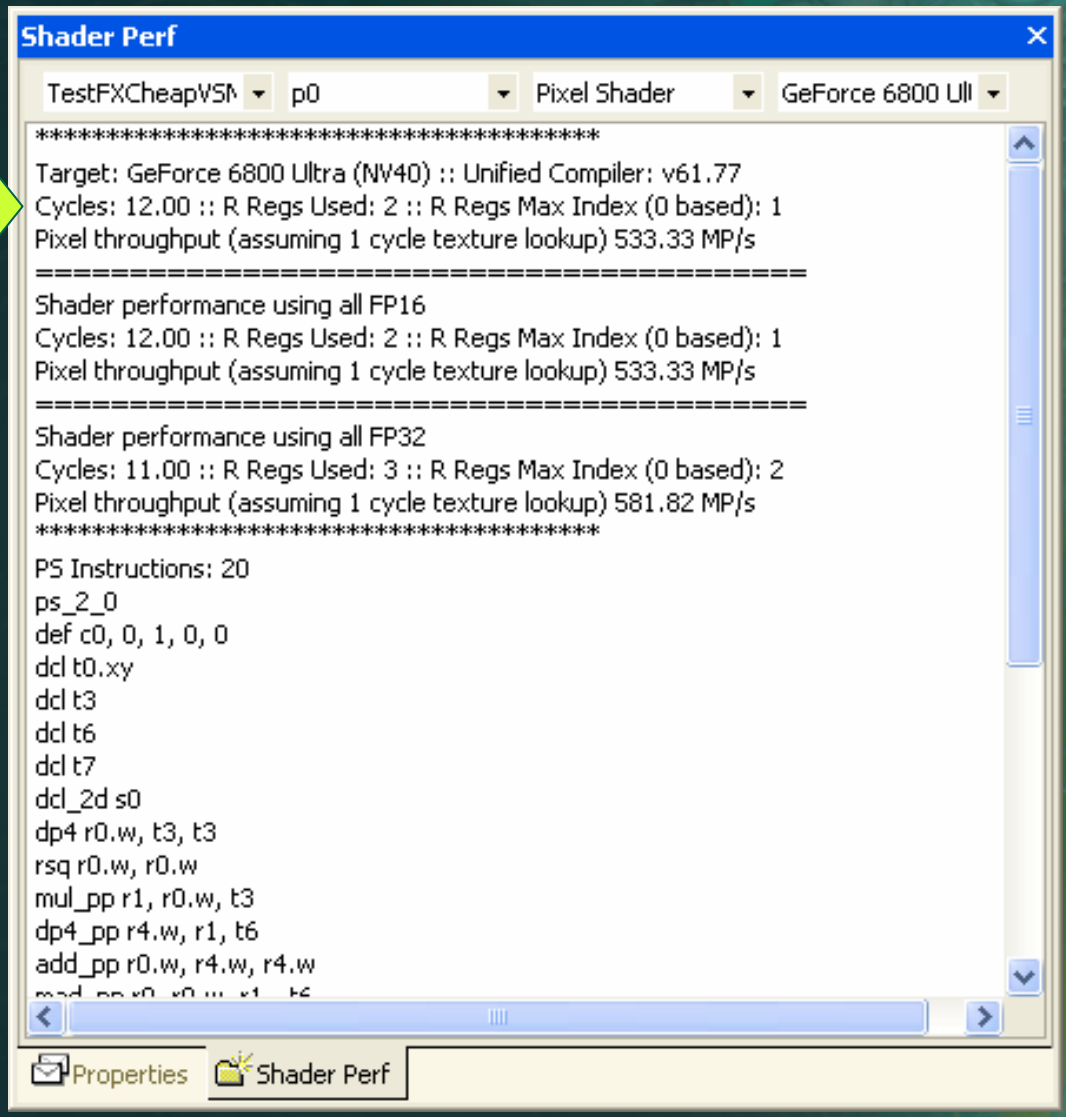
Practice: Example 3



32 cycles BAD

Practice: Example 3

12 cycles GOOD

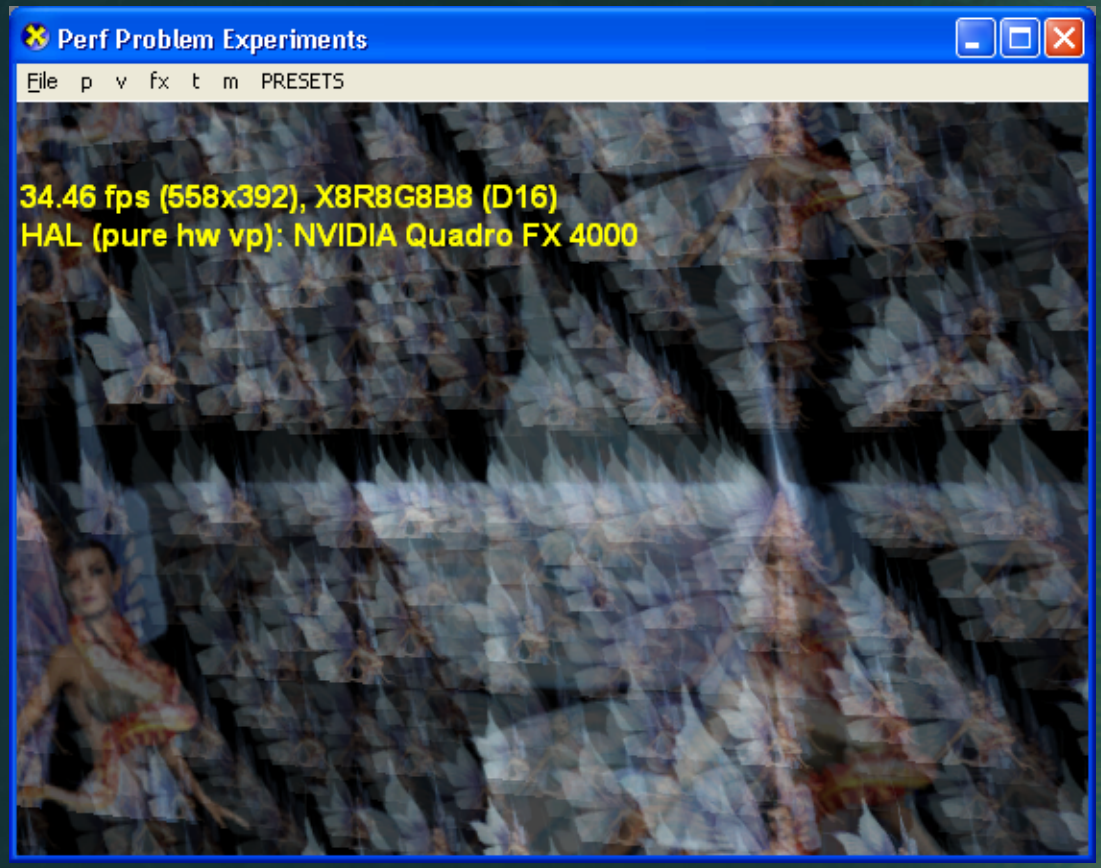


Practice: Example 3

- What changed?
  - Moved math that was constant across the triangle into the vertex shader
  - Used ‘half’ instead of ‘float’
  - Got rid of normalize where it wasn’t necessary
    - See Normalization Heuristics
    - http://developer.nvidia.com

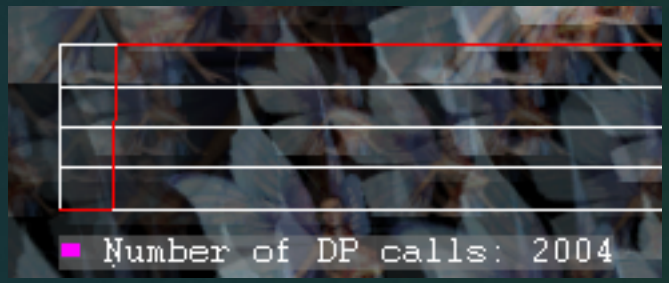
Practice: Example 4

- The last one
  - Audience: there are no more prizes, but we've locked the doors



Practice: Example 4

- Too many batches
  - Was sending every quad as it’s own batch
  - Instead, group quads into one big VB then send that with one call



Practice: Example 4

- What if they use different textures?
  - Use texture atlases
  - Put the two textures into a single texture and use a vertex and pixel shader to offset the texture coordinates

Agenda

- Performance Tools Survey
- Performance Methodologies and Practice
- Next generation Performance Tools
- Conclusion
- Q & A

Next Generation Performance Tools

- NVIDIA Performance Kit (PerfKit)
  - Instrumented Driver
  - NVIDIA Developer Control Panel (NVDevCPL)
  - NVIDIA Plug-in for Microsoft PIX for Windows
  - Sample Code for DirectX

Problem

Application

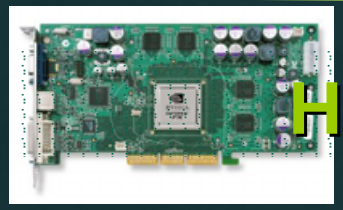
Common Profilers

Microsoft DIRECTX® API

PIX for Windows

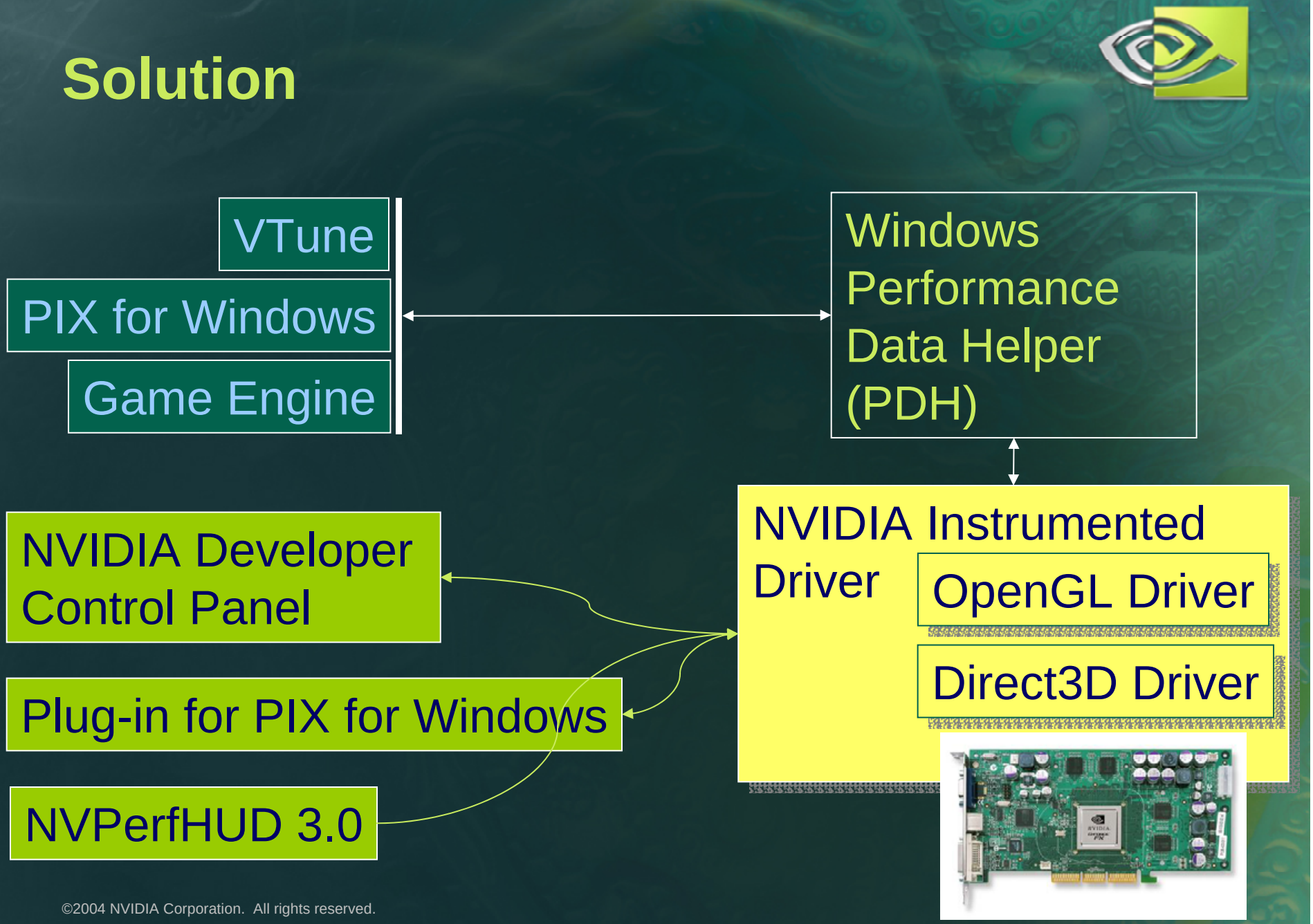
Driver

How to evaluate performance here?



Hardware

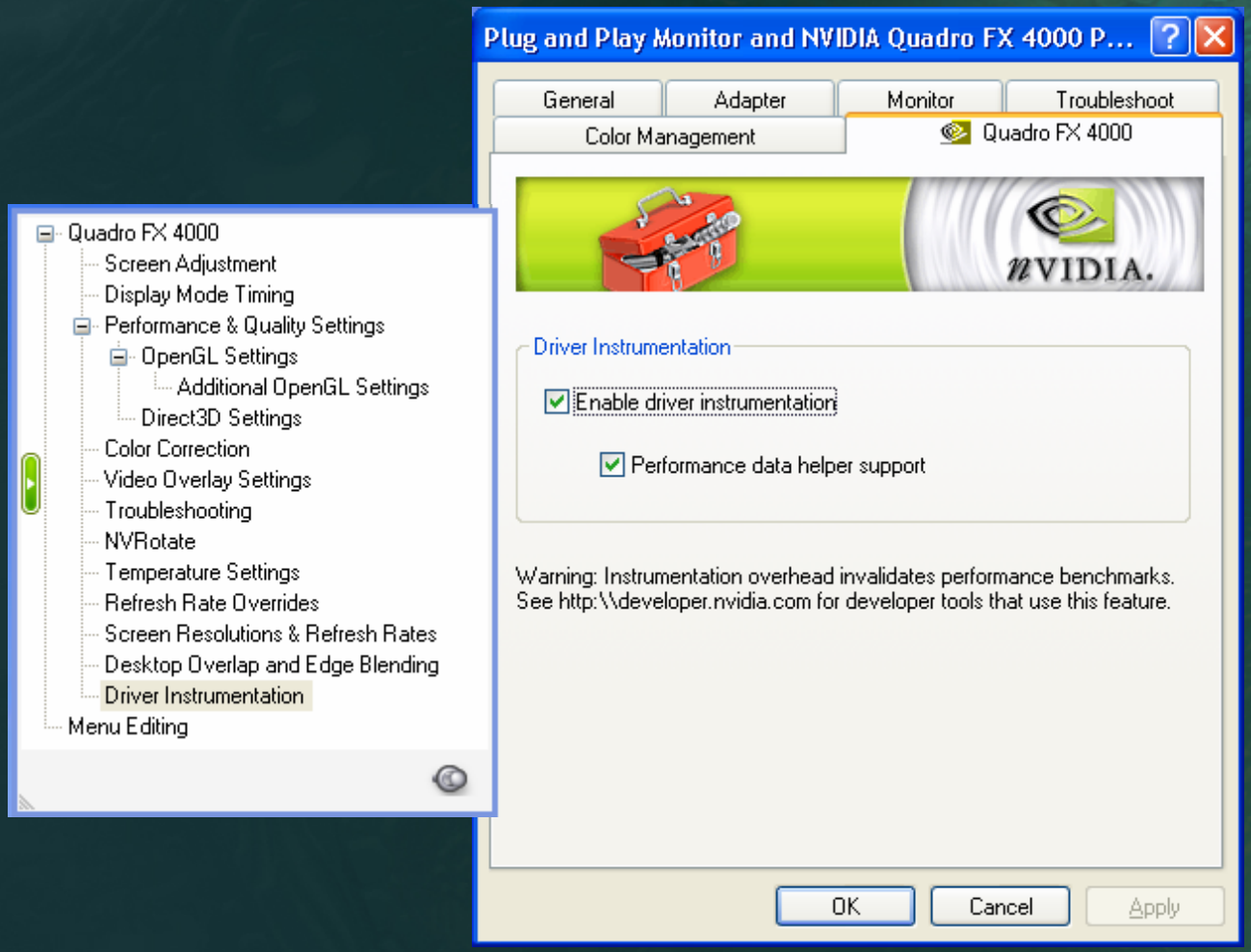
Solution



Instrumented Driver

- Special Instrumented Driver
  - Built with regular drivers
  - Includes NVPMAPI.DLL
- Exposes Driver and HW Performance Counters
- Compatible with Windows WMI and PDH
- New Driver Instrumentation tab in NVIDIA Display Control Panel

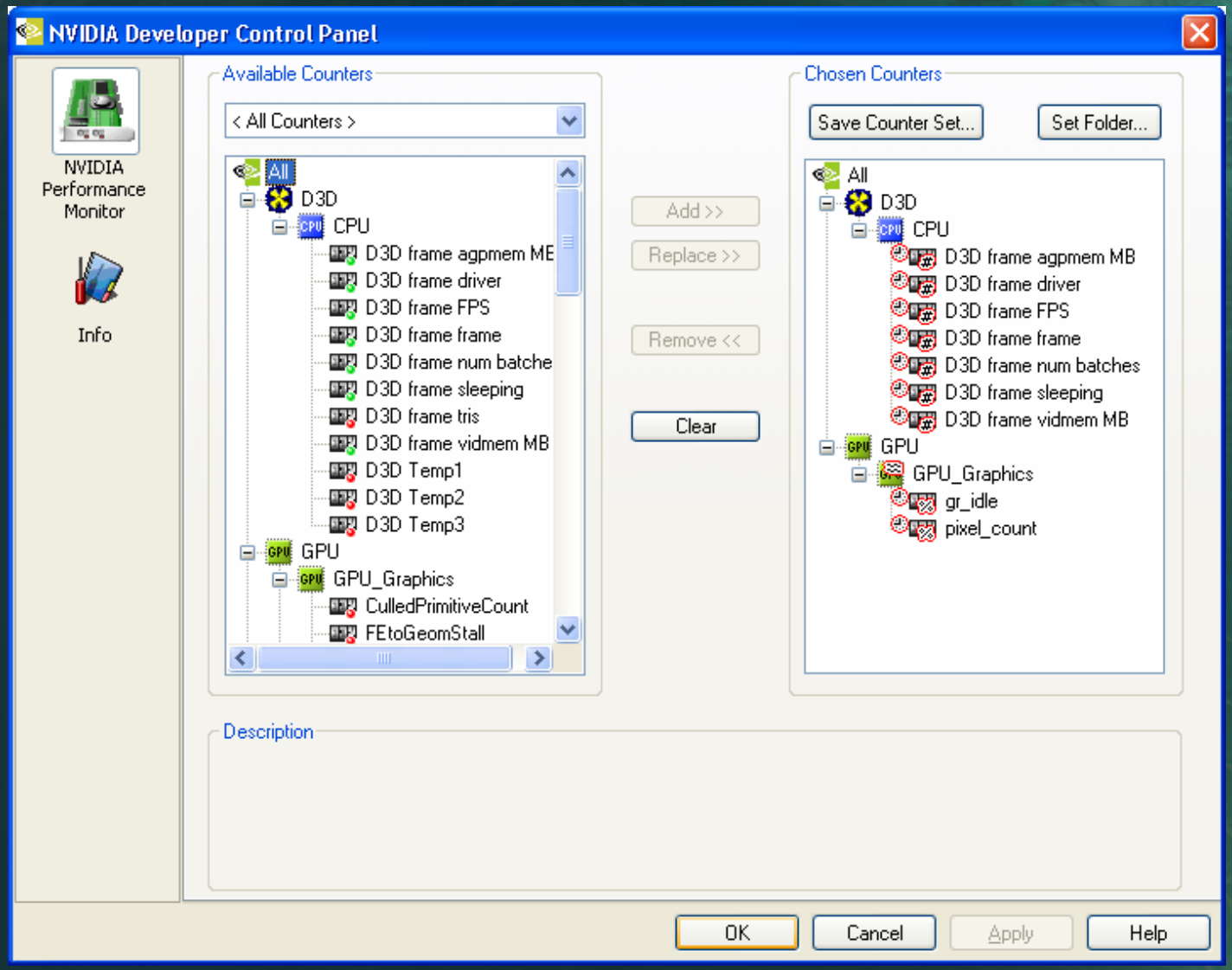
Instrumented Driver



Developer Control Panel

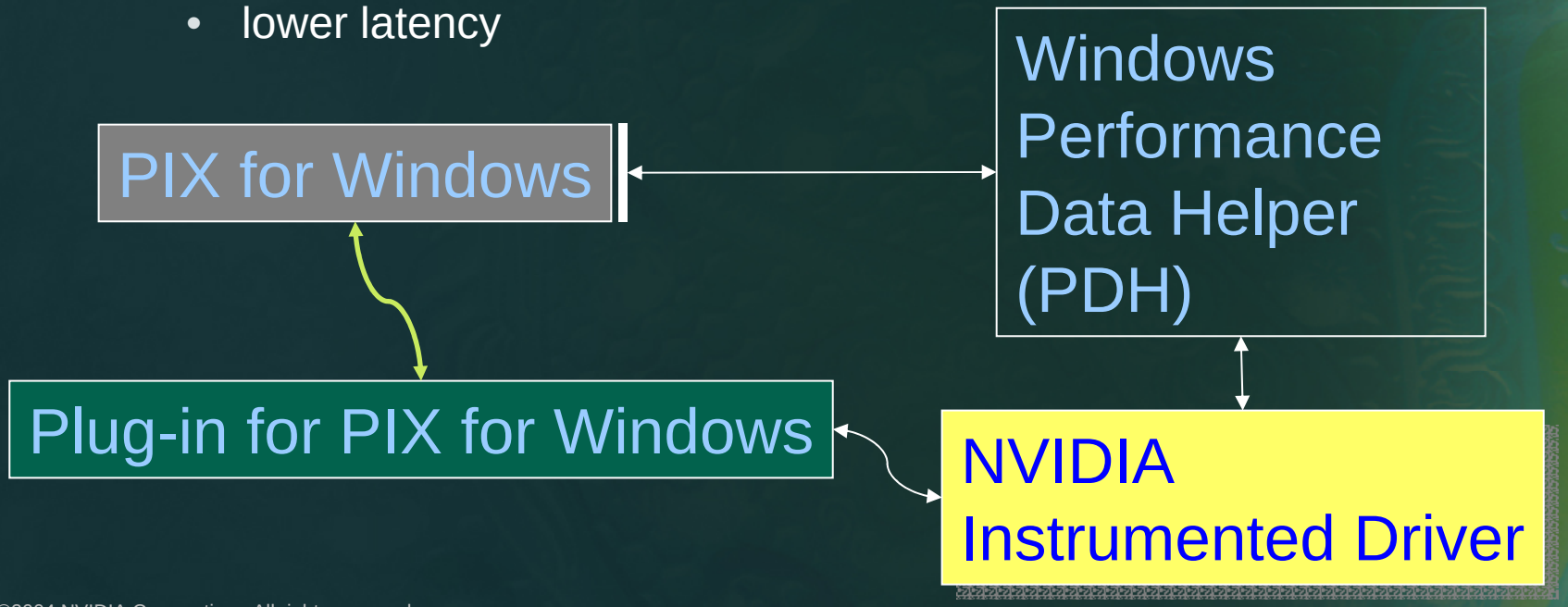
- Control per-counter specifics
  - Enabled or not
  - Raw values or % values
  - Etc.
- Manage multiple counter-sets
  - Tray Icon: fast application of presets
- Provides HW specific information

Developer Control Panel: Demo

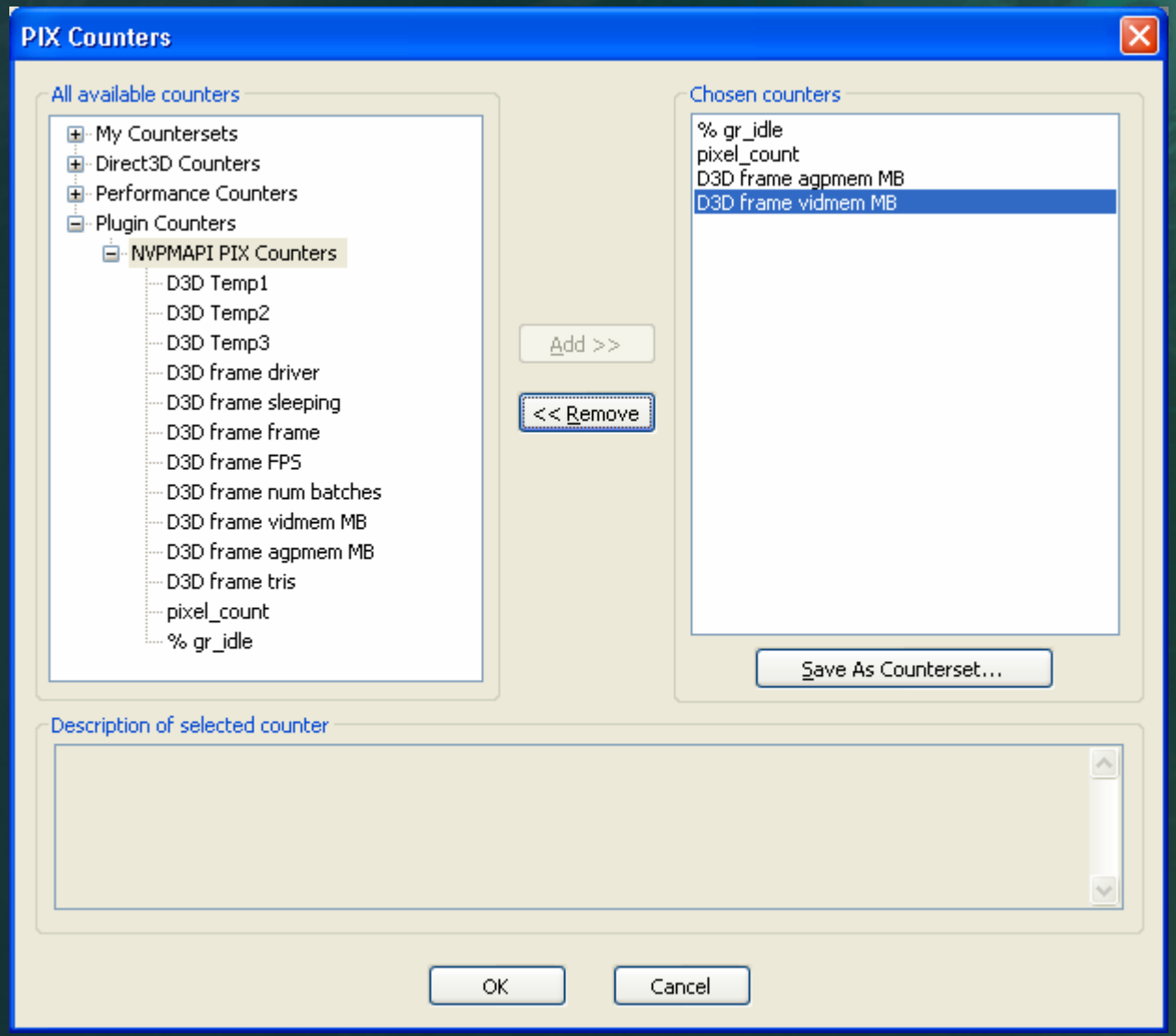


PIX for Windows Plug-in

- NVIDIA's performance counters
  - PIX's PDH adaptor
  - NVIDIA's Pix Plug-in
    - higher frequency
    - lower latency



Plug-in for PIX: Demo



NVPerfKit Code Samples

- Includes C++ helper classes for PDH access and display
  - PDHHelper
  - Trace<T>
  - TraceDisplay
    - Various display types
    - Direct3D implementation
- Sample Code and App
  - Illustrates sampling issues and dynamic reconfigurability

Conclusion

- Comprehensive Suite of Performance Tools
  - performance information at all levels
    - Direct3D API
    - Direct3D Driver
    - Hardware
- Provided in a variety of venues
    - Microsoft WMI/PDH
    - Microsoft PIX for Windows
    - User application
    - NVPerfHUD

Questions?

- What else can we do for you?
  - sdkfeedback@nvidia.com