

Terrain Rendering using GPU-Based Geometry Clipmaps

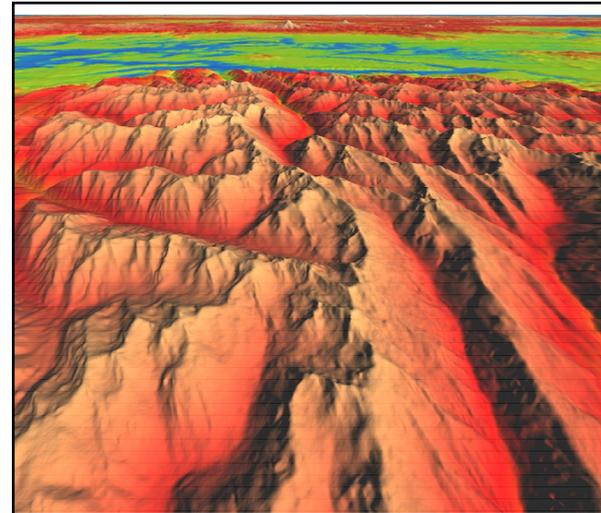
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Microsoft Research



Terrain Rendering Challenges

- Regular grid (image) of height values

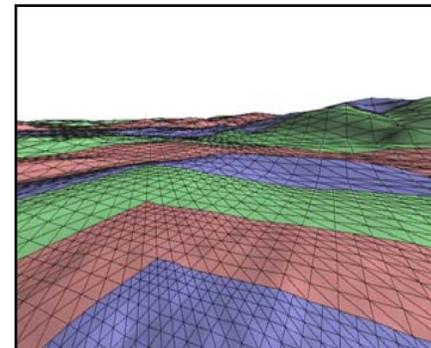
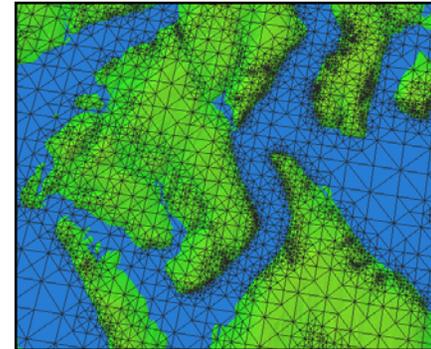
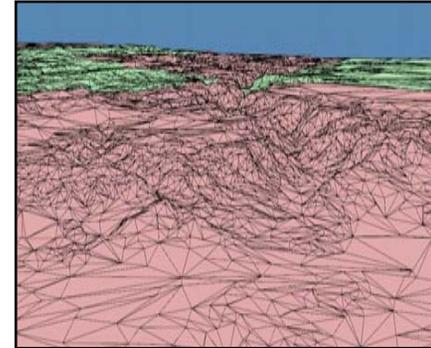


- Concise storage → No paging hiccups
- Real-Time frame rates → 60 fps
- Visual continuity → No temporal pops



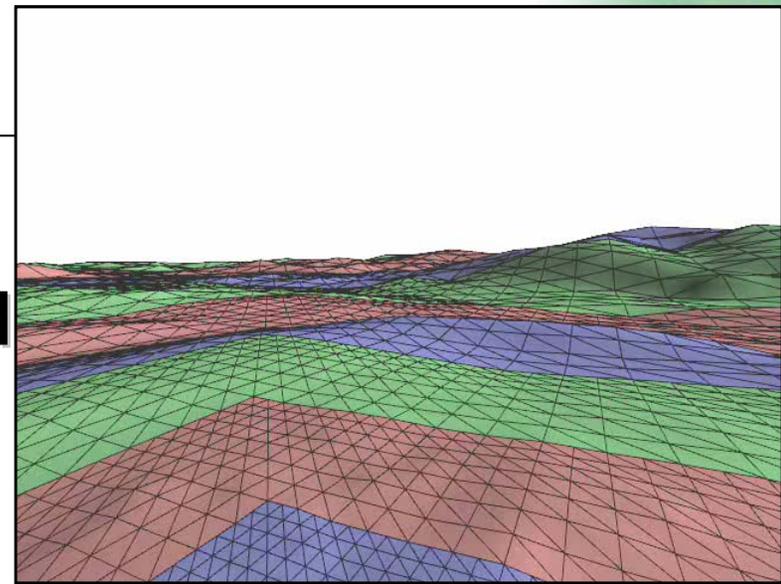
A Change of Focus

- Hoppe 1998 - Highly irregular Connectivity
- Lindstrom 1996 - Semi-regular Connectivity
- Losasso & Hoppe 2004 - Totally regular Connectivity

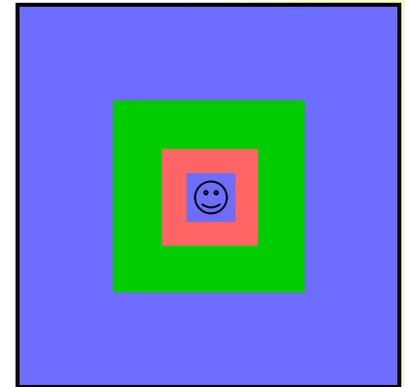
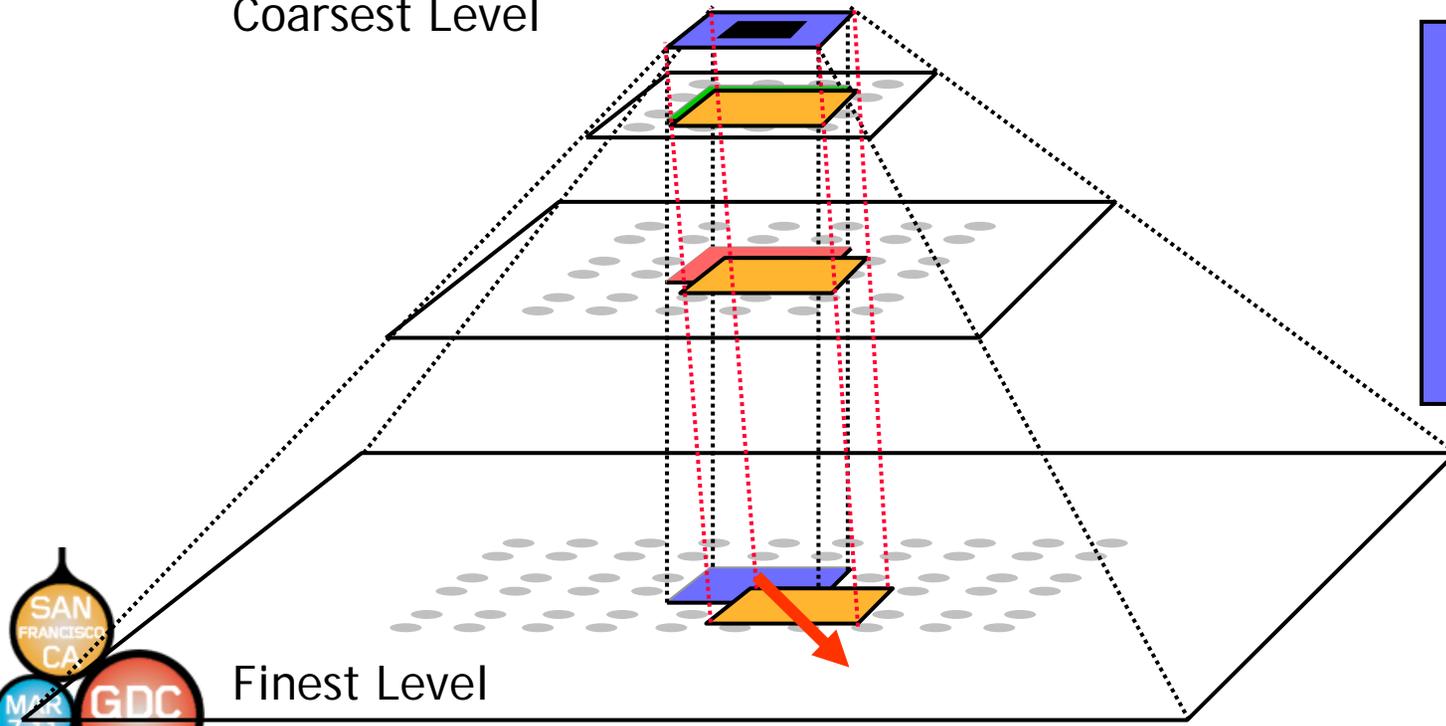


Geometry Clipmaps

- Terrain as mipmap pyramid
- LOD using nested grids



Coarsest Level

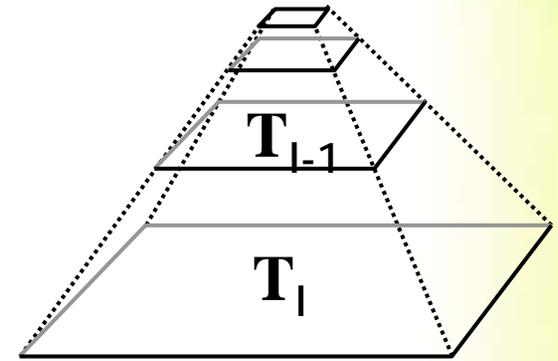


Terrain Compression

- Store coarsest level + inter-level residuals

$$R_l = T_l - U(T_{l-1})$$

$$\tilde{R}_l = \textit{compress}(R_l)$$



- Reconstruction

$$T_l = U(T_{l-1}) + \textit{decompress}(\tilde{R})$$



Why GPU?

- Much less CPU utilization
- Very little AGP/PCIe bus utilization
- Small system memory requirement
- Small video memory requirement
- Significant rendering speedup



GPU Implementation Overview

- DirectX 9.0c - support for Shader Model 3.0
- HLSL code available on book's CD
- Store data as textures (in video memory)
 - Elevation data – 32-bit 1-channel texture
 - Residual data – 32-bit 1-channel texture
 - Normal data – 8-bit 4-channel texture
- Update parts of texture that change



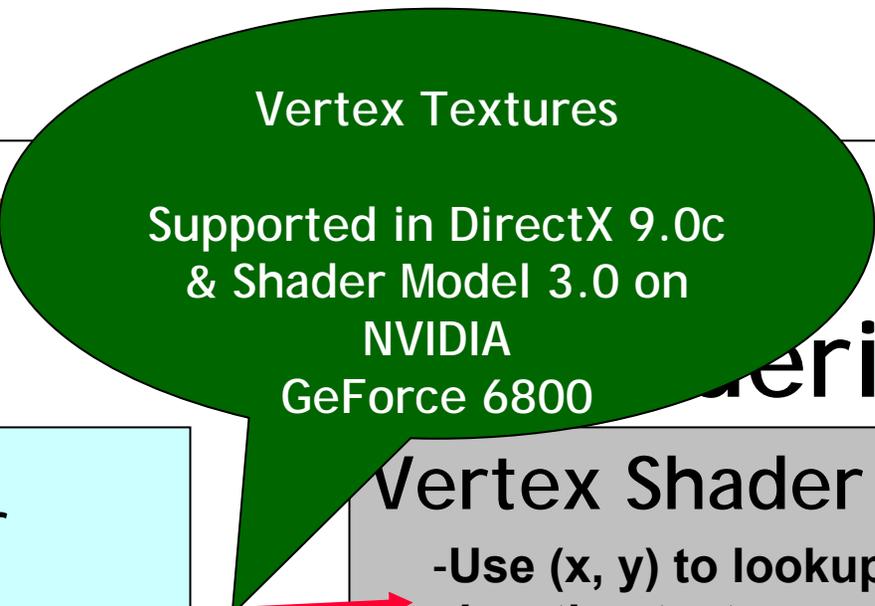
System Design

Update

- Upsample coarser level elevation texture
- Add residuals
- Update normal map texture

Vertex Textures

Supported in DirectX 9.0c
& Shader Model 3.0 on
NVIDIA
GeForce 6800



Vertex Shader

- Use (x, y) to lookup z value in elevation texture
- Compute α
- Blend Geometry

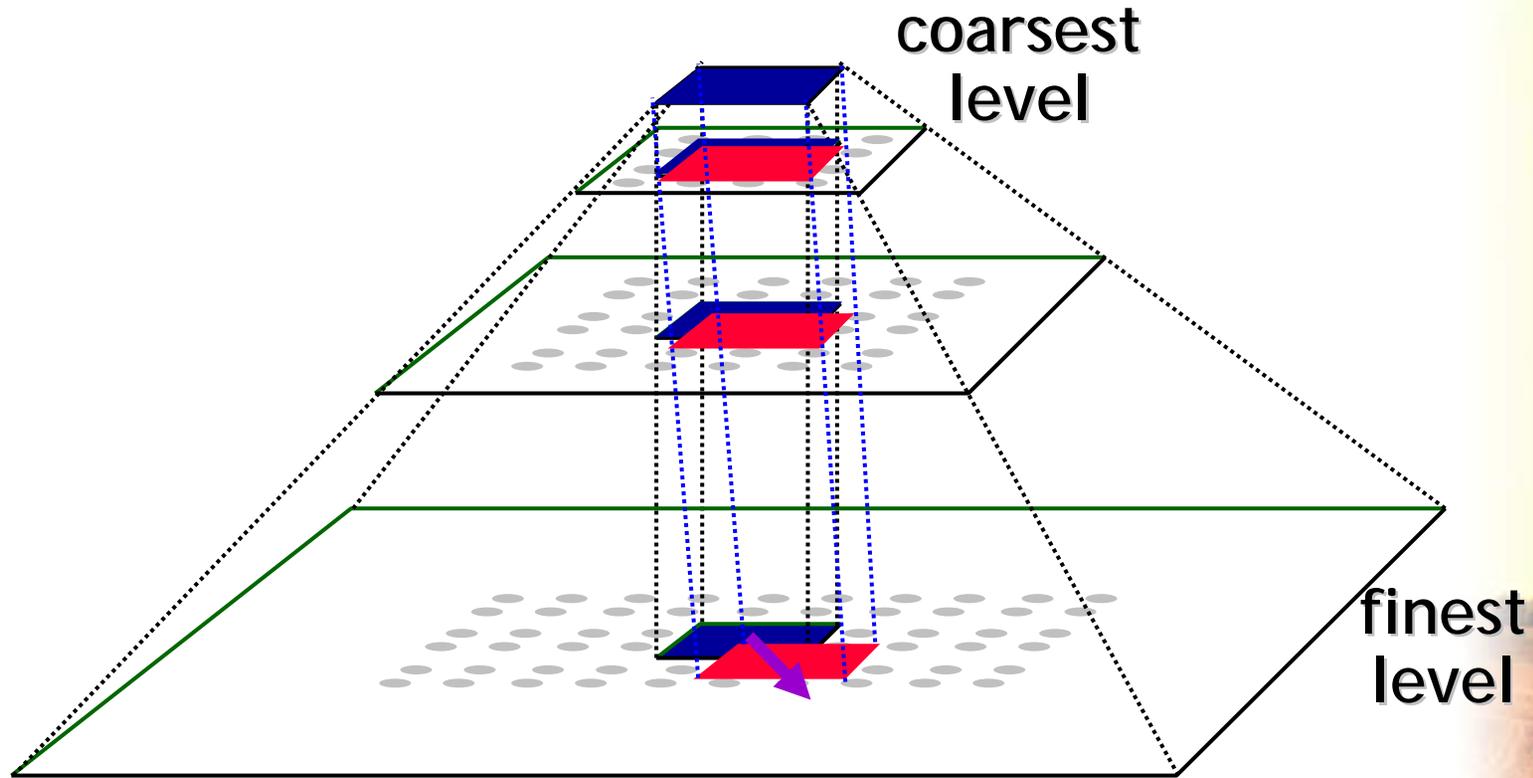
Pixel Shader

- Blend normals
- Does the shading
- Texture lookup

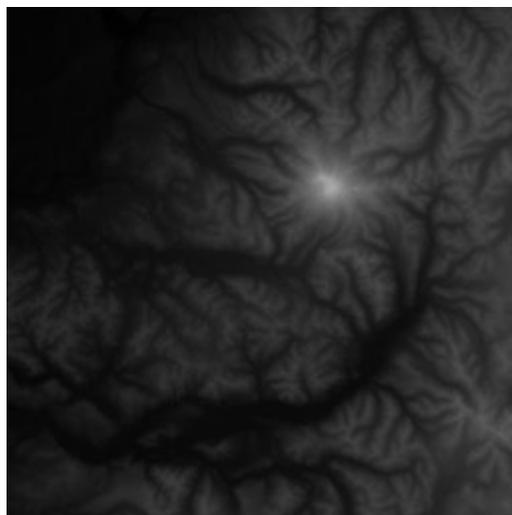
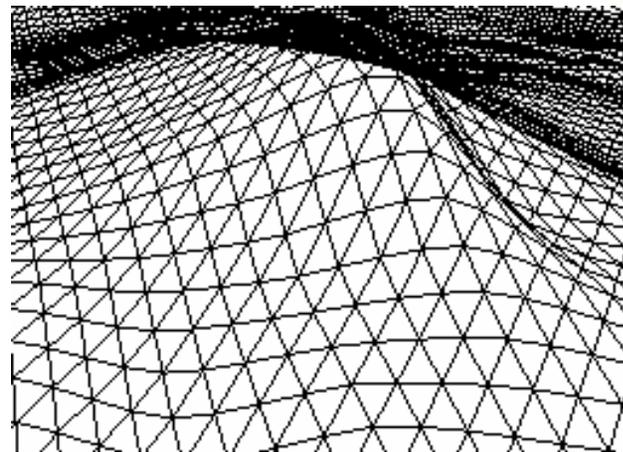
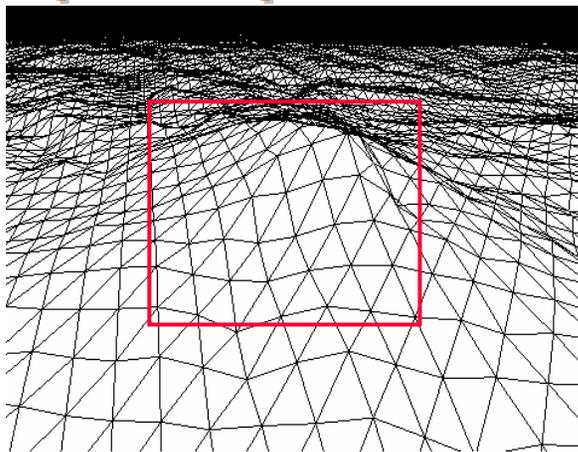


Clipmap Update

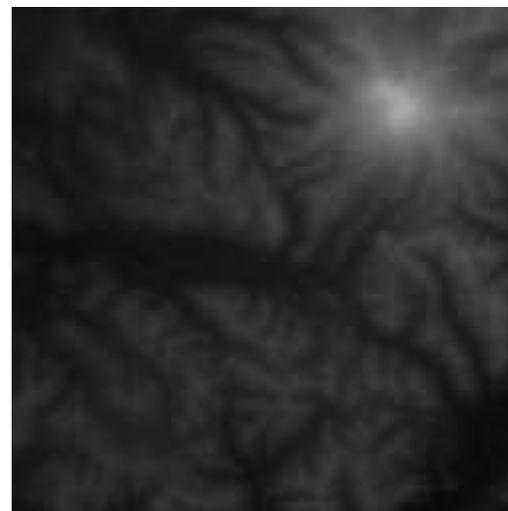
- Shift clipmap levels as user moves



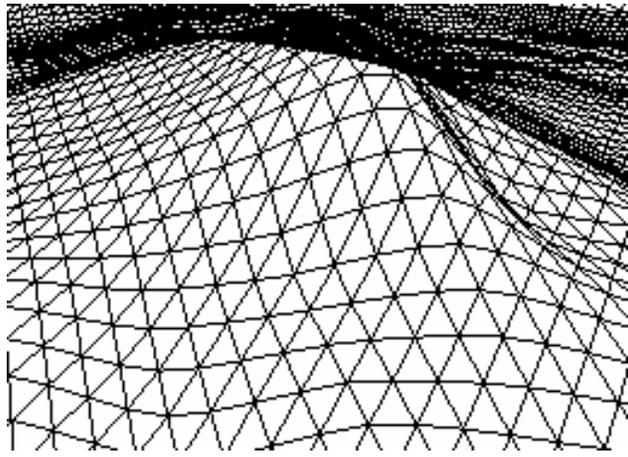
Upsample



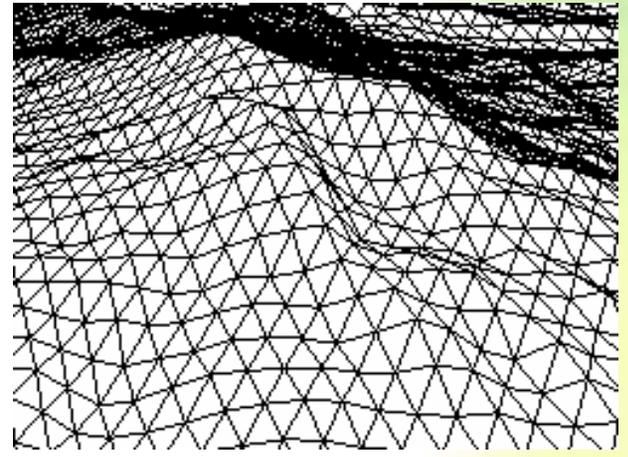
GPU
→



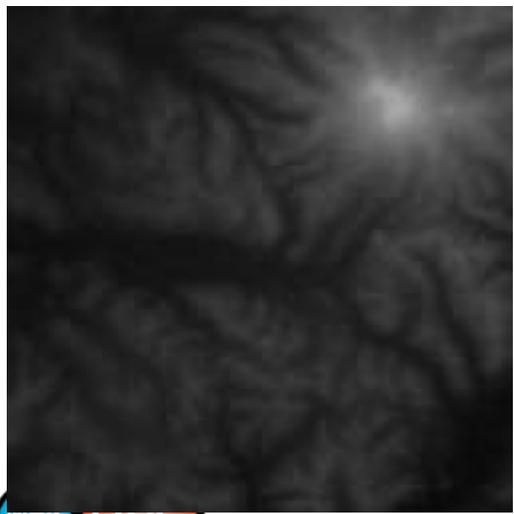
Add residuals



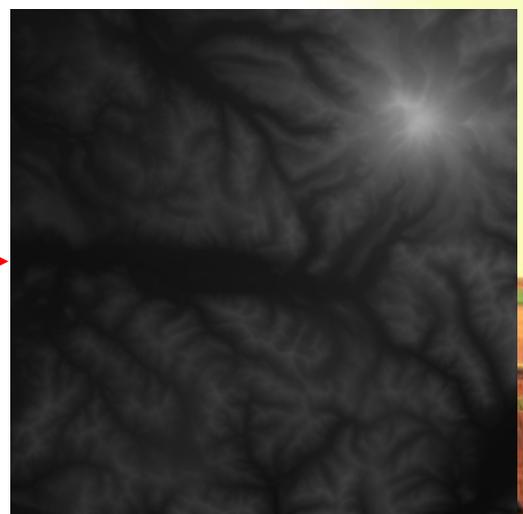
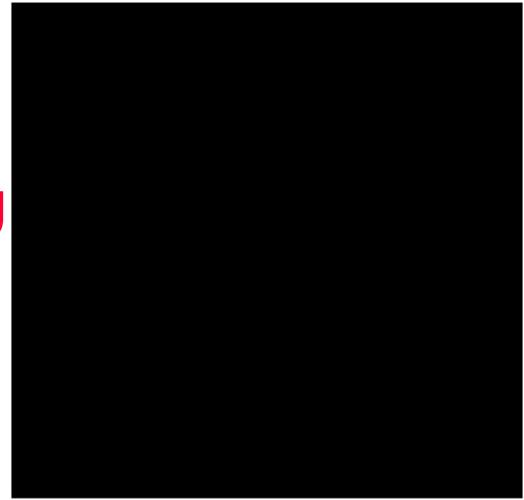
System Memory
Compressed residuals
(350MB for US)



ROI decomposition (CPU)



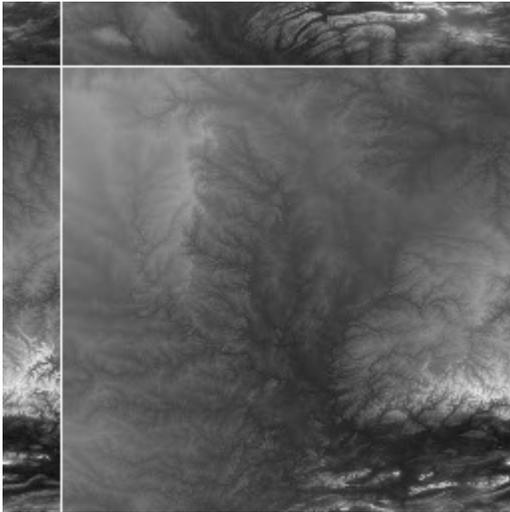
GPU
+



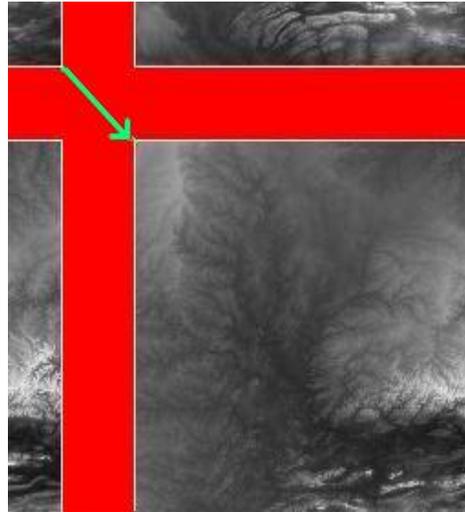
Residual Image in video memory



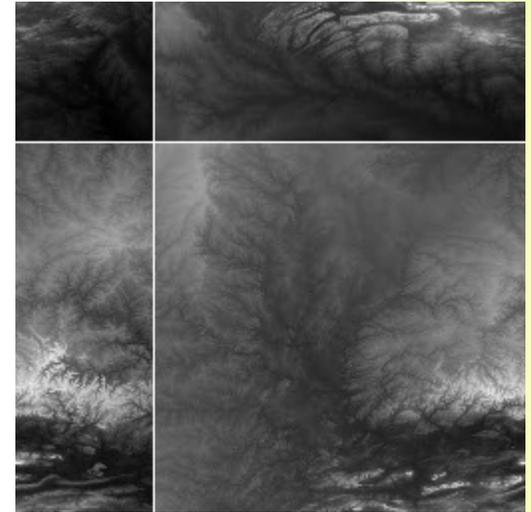
Incremental update



Before update



Update region

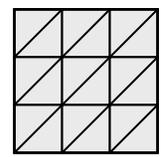
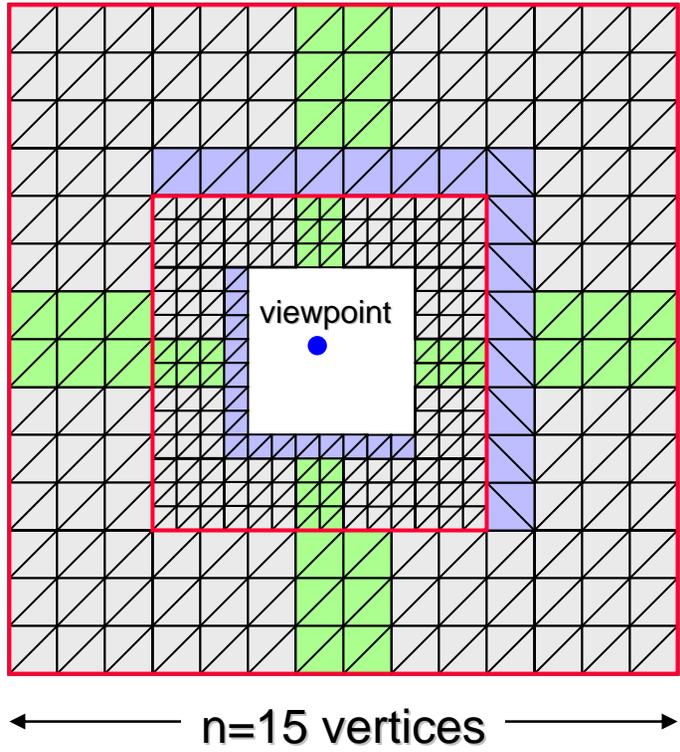


After update

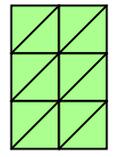


Individual Clipmap Levels

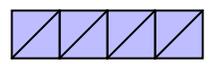
Example: $n=15, m=4$



$m \times m$ block



$m \times 3$ ring fix-up



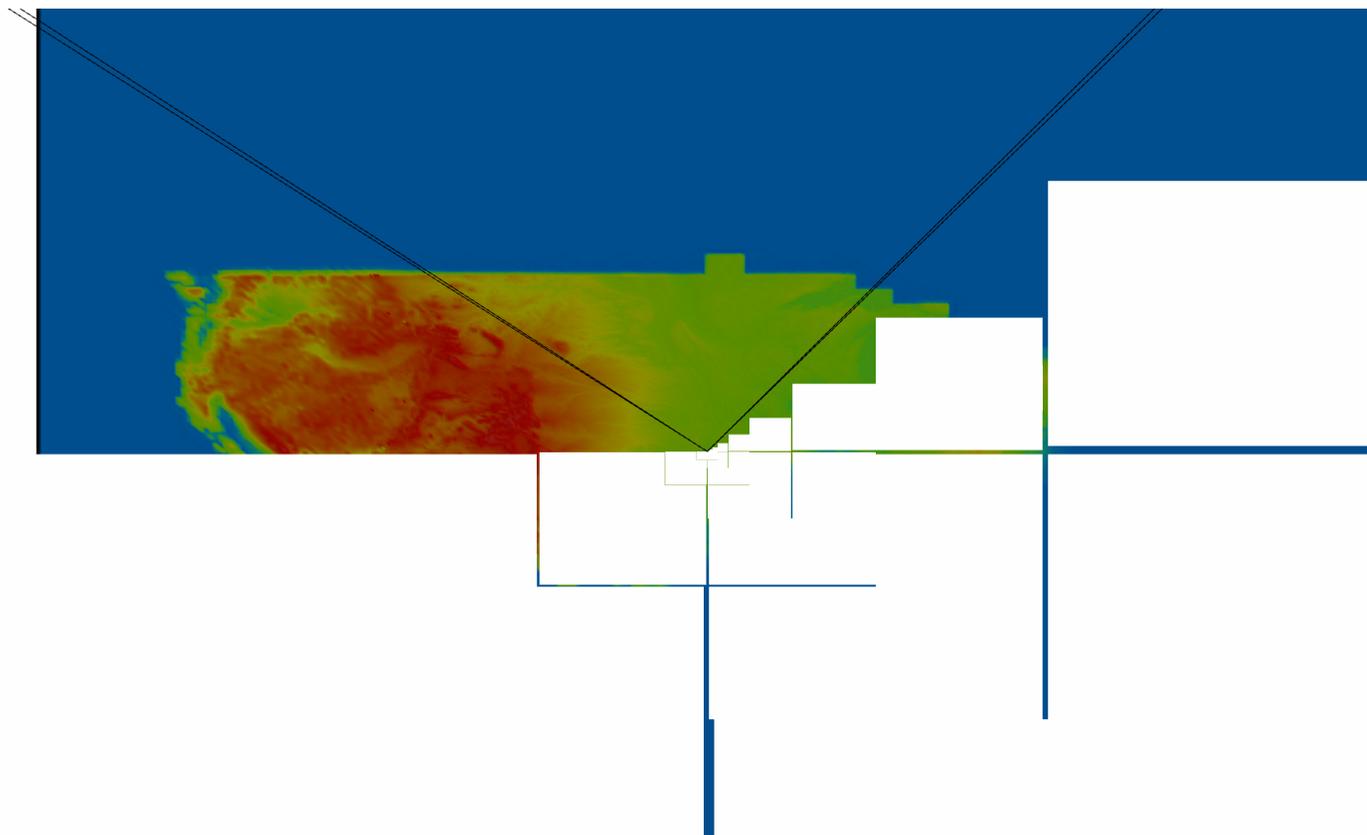
$(2m+1) \times 2$ interior trim

outer degenerate tri.

- See Section 2.3.2 in book



View-frustum culling



- Culling done at block level on CPU
- 2-3x speedup



Timing Results

	Previous Implementation	Current Implementation
Upsampling	3 ms	1.3ms
Decompression	8 ms	8 ms
Normal Map Computation	11 ms	0.6 ms



Performance

- Synthesized terrain
 - 130 frames/second (render-bound)
 - 120 frames/second during user motion
 - 60 million triangles per second
 - CPU utilization: ~0
 - AGP bus utilization: ~0
- Decompressed terrain
 - 87 frames/second during viewer motion
 - Decompression on CPU bottleneck

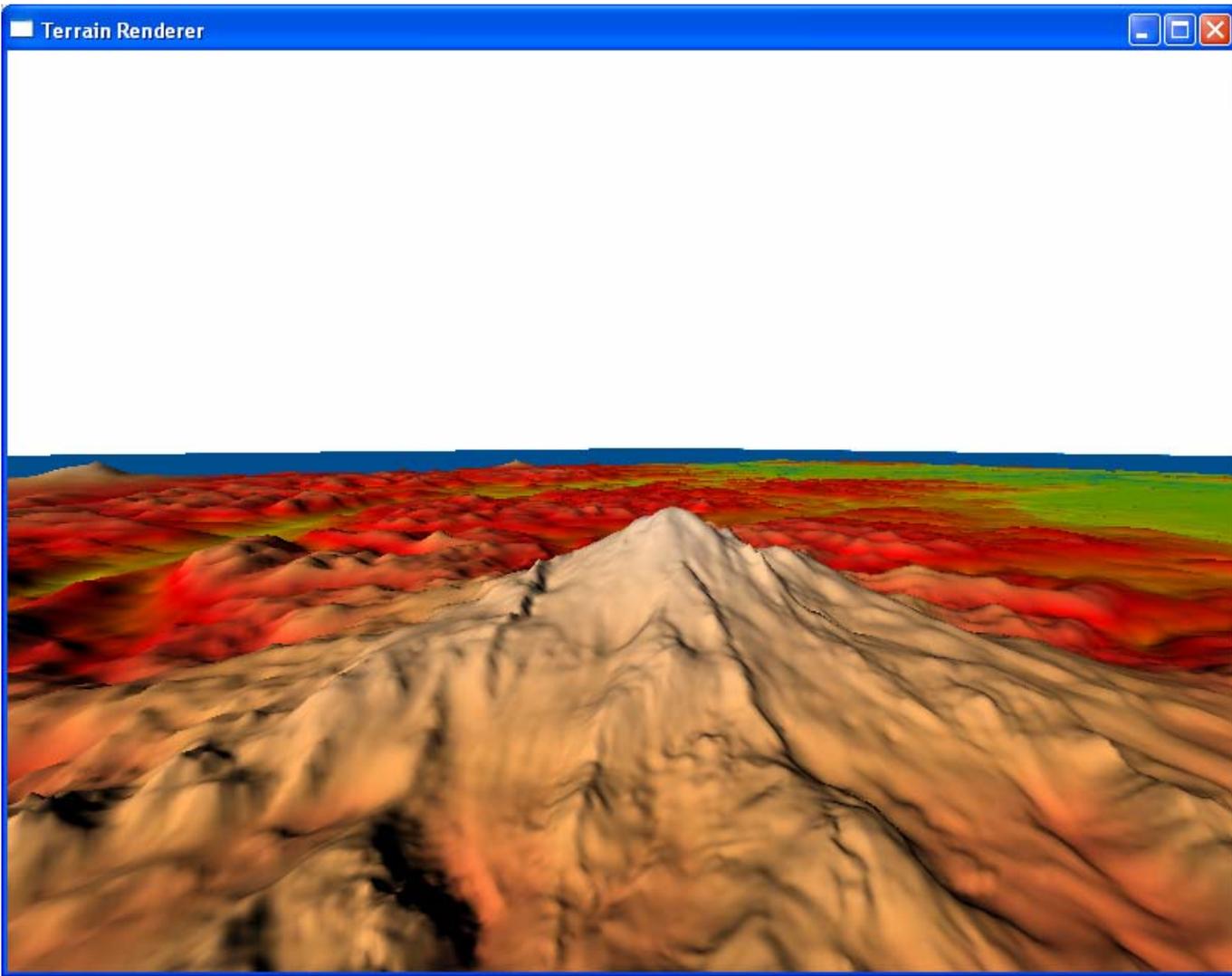


Summary

- Lots of Real-World Applications
 - Games
 - Flight/driving Simulators
 - Virtual Environments
 - Networked Viewer
- Advantages of current framework
 - High compression ratios
 - Terrain synthesis
 - Collision detection within GPU



Demo



Questions?

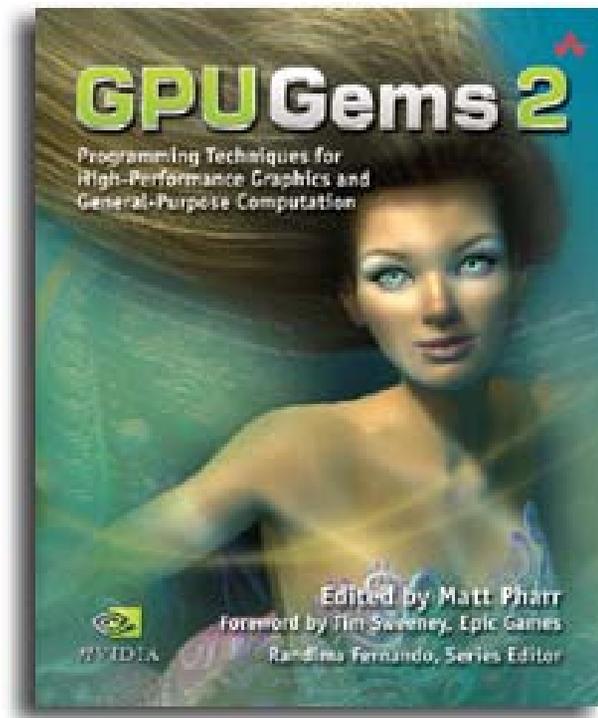
- See GPU Gems 2, Chapter 2
- <http://developer.nvidia.com>
The Source for GPU Programming
- arul@cs.utah.edu
- Slides available online



GPU Gems 2

Programming Techniques for High-Performance Graphics and General-Purpose Computation

- 880 full-color pages, 330 figures, hard cover
- \$59.99
- Experts from universities and industry



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